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This product uses the following source code, subject to the terms of the GPL license. The applications busybox V0.60.2; dosfstools V2.9; linux-tpdf V0.17; ppp V2.4.0; utelnet V0.1.1. The library grx V2.4.4. The linux kernel V2.4.4. The linux boot ppcboot V1.1.3. If you would like to have a CD copy of this source code sent to you, send 10 Euros to Fagor Automation for shipping and handling.
INDEX

PROGRAMMING ERRORS .................................................................5
BLOCK PREPARATION AND EXECUTION ERRORS ..................33
HARDWARE ERRORS .................................................................53
PLC ERRORS ............................................................................61
SERVO ERRORS ........................................................................63
CAN ERRORS .............................................................................75
TABLE DATA ERRORS ..............................................................81
ERRORS OF THE TC WORK MODE ..........................................85
## PROGRAMMING ERRORS

### 0001 ‘Empty line’

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The possible causes are:

1. When trying to enter into a program or execute an empty block or containing the label (block number).
2. In the “Pattern repeat canned cycle (G66)”, “Roughing canned cycle along the X axis (G68)” or “Roughing canned cycle along the Z axis (G69)” when parameter “S” (beginning of profile) is greater than parameter “E” (end of profile).

**SOLUTION** The solution for each cause is:

1. The CNC cannot enter into the program or execute an empty line. To enter an empty line in the program, use the “;” symbol at the beginning of that block. The CNC will ignore the rest of the block.
2. The value of parameter “S” (block where the profile definition begins) must be lower than the value of parameter “E” (block where the profile definition ends).

### 0002 ‘Improper data’

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The possible causes are:

1. When editing an axis coordinate after the cutting conditions (F, S, T or D) or the “M” functions.
2. When the marks of the block skip (conditional block /1, /2 or /3) are not at the beginning of the block.
3. When programming a block number greater than 99999999 while programming in ISO code.
4. While programming in high-level, the value of the RPT instruction exceeds 9999.

**SOLUTION** The solution for each cause is:

1. Remember the programming order.
2. Remember the programming order.
   - Block skip (conditional block /1, /2 or /3).
   - Label (N).
   - “G” functions.
   - Axis coordinates. (X, Y, Z...).
   - Machining conditions (F, S, T, D).
   - “M” functions.
3. Correct the syntax of the block. Program the labels between 0 and 99999999.
4. Correct the syntax of the block. Program a number of repetitions between 0 and 9999.

### 0003 ‘Improper data order.’

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The machining conditions or the tool data have been programmed in the wrong order.

**SOLUTION** Remember that the programming order is:

```
... F...S...T...D......
```

All the data need not be programmed.
**Error solution**

---

**0004  'No more information allowed in the block.'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The possible causes are:

1. When editing a "G" function after an axis coordinate.
2. When trying to edit some data after a "G" function (or after its associated parameters) which must go alone in the block (or which only admits its own associated data).
3. When assigning a numeric value to a parameter that does not need it.

**SOLUTION** The solution for each cause is:

1. Remember that the programming order is:
   - Block skip (conditional block /1, /2 or /3).
   - Label (N).
   - "G" functions.
   - Axis coordinates. (X, Y, Z...).
   - Machining conditions (F, S, T, D).
   - "M" functions.
2. There are some "G" functions which carry associated data in the block. Maybe, this type of functions do not let program other type of information after their associated parameters. On the other hand, neither machining conditions, (F, S), tool data (T, D) nor "M" functions may be programmed.
3. There are some "G" functions having certain parameters associated to them which do not need to be defined with values.

---

**0005  'Repeated information'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The same data has been entered twice in a block.

**SOLUTION** Correct the syntax of the block. The same data cannot be defined twice in a block.

---

**0006  'Improper data format'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** While defining the parameters of a machining canned cycle, a negative value has been assigned to a parameter which only admits positive values.

**SOLUTION** Verify the format of the canned cycle. In some canned cycles, there are parameters which only accept positive values.

---

**0007  'Incompatible G functions.'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The possible causes are:

1. When programming in the same block two "G" functions which are incompatible with each other.
2. When trying to define a canned cycle in a block containing a nonlinear movement (G02, G03, G08, G09, G33).

**SOLUTION** The solution for each cause is:

1. There are groups of "G" functions which cannot go together in the block because they involve actions incompatible with each other. For example:
   - G01/G02: Linear and circular interpolation
   - G41/G42: Left-hand or right-hand tool radius compensation.
   - This type of functions must be programmed in different blocks.
2. A canned cycle must be defined in a block containing a linear movement. In other words, to define a cycle, a "G00" or a "G01" must be active. Nonlinear movements (G02, G03, G08 and G09) may be defined in the blocks following the profile definition.

---

**0008  'Nonexistent G function'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** A nonexistent "G" function has been programmed.

**SOLUTION** Check the syntax of the block and verify that a different "G" function is not being edited by mistake.
0009 'No more G functions allowed'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE A "G" function has been programmed after the machining conditions or after the tool data.
SOLUTION Remember that the programming order is:
- Block skip (conditional block /1, /2 or /3).
- Label (N).
- "G" functions.
- Axis coordinates (X,Y,Z...).
- Machining conditions (F, S, T, D).
- "M" functions.

0010 'No more M functions allowed'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE More than 7 "M" functions have been programmed in a block.
SOLUTION The CNC does not let program more than 7 "M" functions in a block. To execute any other functions, write them in a separate block. The "M" functions may go alone in a block.

0011 'This G or M function must be alone.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE The block contains either a "G" or an "M" function that must go alone in the block.
SOLUTION Write it alone in the block.

0012 'Program F, S, T, D before the M functions.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE A machining condition (F, S) or tool data (T, D) has been programmed after the "M" functions.
SOLUTION Remember that the programming order is:
... F...S...T...D...M...
Up to 7 "M" functions may be programmed.
All the data need not be programmed.

0013 'Program G30 D +/-359.9999'

No explanation required.

0014 'Do not program labels by parameters.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE A label (block number) has been defined with a parameter.
SOLUTION Programming the block number is optional, but it cannot be defined with a parameter. It can only be defined with a number between 0 and 99999999.

0015 'Number of repetitions not possible.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE A repetition has been programmed wrong or the block does not admit repetitions.
SOLUTION High level instructions do not admit a number of repetitions at the end of the block. To do a repetition, assign to the block to be repeated a label (block number) and use the RPT instruction.

0016 'Program: G15 or G15 C.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An attempt has been made to execute an operation on the "C" axis, but the axis is not active.
SOLUTION In order to operate with the "C" axis, it must be activated first using the "G15" function.

0017 'Program: G16 axis-axis.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE In the function "Main plane selection by two axes (G16)" one of the two parameters for the axes has not been programmed.
SOLUTION Check the syntax of the block. The definition of the "G16" function requires the name of the axes defining the new work plane.
0018 'Program: G22 K(1/2/3/4/5) S(0/1/2).'

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** In the function "Enable/Disable work zones (G22)" the type of enable or disable of the work zone has not been defined or it has been assigned the wrong value.

**SOLUTION** The parameter for enabling or disabling the work zones “S” must always be programmed and it may take the following values.

- S=0: The work zone is disabled.
- S=1: It is enabled as a no-entry zone.
- S=2: It is enabled as a no-exit zone.

0019 'Program: work zone K1, K2, K3, K4 or K5.'

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The possible causes are:

1. A “G20”, “G21” or “G22” function has been programmed without defining the work zone K1, K2, K3, K4 or K5
2. The programmed work zone is smaller than 0 or greater than 5.

**SOLUTION** The solution for each cause is:

1. The programming format for functions “G20”, “G21” and “G22” is:
   
   - G20 K...X...C±5.5 Definition of lower work zone limits.
   - G21 K...X...C±5.5 Definition of upper work zone limits.
   - G22 K...S... Define/disabled work zones.

   Where:
   - K Is the work zone.
   - X...C Are the axes where the limits are defined.
   - S Is the type of work zone enable.
2. The "K" work zone may only have the values of K1, K2, K3, K4 or K5.

0020 ‘Program G36-G39 with R+5.5.’

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** In the “G36” or “G39” function, the “R” parameter has not been programmed or it has been assigned a negative value.

**SOLUTION** To define “G36” or “G39”, parameter “R” must also be defined and with a positive value.

- G36 R= Rounding radius.
- G39 R= Distance between the end of the programmed path and the point to be chamfered.

0021 ‘Program: G72 S5.5 or axi(e)s.’

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The possible causes are:

1. When programming a general scaling factor (G72) without the scaling factor to apply.
2. When programming a particular scaling factor (G72) to several axes, but the axes have been defined in the wrong order.

**SOLUTION** Remember that the programming format for this function is:

- G72 S5.5 When applying a general scaling factor (to all axes).
- G72 X...C5.5 When applying a particular scaling factor to one or several axes.
0023 ‘Block incompatible when defining a profile.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE In the set of blocks defining a profile, there is a block containing a «G» function that cannot be part of the profile definition.

SOLUTION The “G” functions available in the profile definition are:
- G00: Beginning of the profile.
- G01: Linear interpolation.
- G02/G03: Clockwise/counterclockwise interpolation.
- G06: Circle center in absolute coordinates.
- G08: Arc tangent to previous path.
- G09: Three point arc.
- G36: Automatic radius blend.
- G39: Chamfer.
- G53: Programming with respect to home.
- G70/G71: Inch/metric programming.
- G90/G91: Programming in absolute/incremental coordinates.
- G93: Polar origin preset.

0024 ‘High level blocks not allowed when defining a profile.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE Within the set of blocks defining a profile, a high level block has been programmed.

SOLUTION Profiles must be defined in ISO code. High level instructions are not allowed (GOTO, MSG, RPT ...).

0025 ‘Program: G77 axes (from 2 to 6) or G77 S.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE In the “axis slaving function (G77)” the parameters for the axes are missing or in “spindle synchronization (G77S) functions the “S” parameter is missing.

SOLUTION In the “axis slaving” function, program at least two axes and in the “spindle synchronization” function, always program the “S” parameter.

0026 ‘Program: G93 I J.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE In the “Polar origin preset (G93)” function, some of the parameters for the new polar origin have not been programmed.

SOLUTION Remember that the programming format for this function is:

G93 I...J...

The “I”, “J” values are optional, but if programmed, both must be programmed and they indicate the new polar origin.

0028 ‘G2 or G3 not allowed when programming a canned cycle.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE A canned cycle has been attempted to execute while the “G02”, “G03” or “G33” functions were active.

SOLUTION To execute a canned cycle, “G02” or “G01” must be active. A “G02” or “G03” function may be programmed previously in the program history. Check that these functions are not active when the canned cycle is defined.
Error solution

**0029 'G84-85: X Z Q R C [D L M F H] I K.'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The parameters of the canned cycle for «Turning of curved sections (G84)» or for «Facing curved sections (G85)» have been programmed wrong. These may be the probable causes:
1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.
3. A parameter has been programmed which does not match the calling format.

**SOLUTION** The following parameters must be programmed in this cycle:
- X-Z Profile starting point
- Q-R Profile end point
- C Depth of pass.
- I-K Distance from the starting point to the arc center.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.

**0030 'G86-87: X Z Q R I B [D L] C [J A].'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The parameters of the canned cycle for «longitudinal threadcutting (G86)» or for «face threadcutting (G87)» have been programmed wrong. These may be the probable causes:
1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.
3. A parameter has been programmed which does not match the calling format.

**SOLUTION** The following parameters must be programmed in this cycle:
- X-Z Starting point of the thread.
- Q-R End point of the thread.
- I Thread depth.
- B Depth of pass.
- C Thread pitch.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.

**0031 'G88-G98: X Z Q R [C D K].'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The parameters of the canned cycle for «grooving along X (G88)» or «grooving along Z (G89)» have been programmed wrong. These may be the probable causes:
1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.
3. A parameter has been programmed which does not match the calling format.

**SOLUTION** The following parameters must be programmed in this cycle:
- X-Z Starting point of the groove.
- Q-R End point of the groove.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.

**0032 'G66: X Z I C [A L M H] S E.'**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The parameters of the «Pattern repeat canned cycle with islands (G66)» have been programmed wrong. These may be the probable causes:
1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.
3. A parameter has been programmed which does not match the calling format.

**SOLUTION** The following parameters must be programmed in this cycle:
- X-Z Profile starting point
- I Remaining stock.
- C Depth of pass.
- S Block where the profile geometry description begins.
- E Block where the profile geometry description ends.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.
Error solution


DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE The parameters of the canned cycle for «roughing along X (G68)» or «roughing along Z (G69)» have been programmed wrong. These may be the probable causes:

1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.
3. A parameter has been programmed which does not match the calling format.

SOLUTION The following parameters must be programmed in this cycle:

- X-Z: Profile starting point
- C: Depth of pass.
- S: Block where the profile geometry description begins.
- E: Block where the profile geometry description ends.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.

0034 ‘G81-G82: X Z Q R C [D L M F H].’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE The parameters of the canned cycle for «Turning of straight sections (G81)» or for «Facing straight sections (G82)» have been programmed wrong. These may be the probable causes:

1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.
3. A parameter has been programmed which does not match the calling format.

SOLUTION The following parameters must be programmed in this cycle:

- X-Z: Profile starting point
- Q-R: Profile end point
- C: Depth of pass.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.

0035 ‘G83: X Z I B [D K H C L R].’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE The parameters have been programmed wrong in the «Axial drilling/tapping cycle (G83)». These may be the probable causes:

1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.
3. A parameter has been programmed which does not match the calling format.

SOLUTION The following parameters must be programmed in this cycle:

- X-Z: Machining position.
- I: Machining depth.
- B: Type of operation.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.


DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE The parameters of the canned cycle for «face drilling or tapping (G60)» or for «longitudinal drilling or tapping (G61)» have been programmed wrong. These may be the probable causes:

1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.
3. A parameter has been programmed which does not match the calling format.

SOLUTION The following parameters must be programmed in this cycle:

- X-Z: Machining position.
- I: Machining depth.
- B: Type of operation.
- Q: Angular position of the first machining operation.
- A: Angular step between machining operations.
- J: Number of machining operations.
- S: Live tool turning speed and direction.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.

**DETECTION**
While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE**
The parameters of the canned cycle for “longitudinal slot milling (G62)” or “face slot milling (G62)” have been programmed wrong. These may be the probable causes:
1. Some mandatory parameter is missing.
2. The parameters of the cycle have not been edited in the correct order.

**SOLUTION**
The following parameters must be programmed in this cycle:
- X, Z Slot position.
- L Slot length.
- I Slot depth.
- Q Angular position of the first slot.
- A Angular step between slots.
- J Number of slots.
- F Feedrate.
- S Live tool turning speed and direction.

The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.

0043 ‘Incomplete Coordinates.’

**DETECTION**
While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE**
The possible causes are:
1. During simulation or execution, when trying to make a movement defined with only one coordinate of the end point or without defining the arc radius while a circular interpolation (G02/G03) is active.
2. During editing, when editing a circular movement (G02/G03) by defining only one coordinate of the end point or not defining the arc radius.

**SOLUTION**
The solution for each cause is:
1. A “G02” or “G03” function may be programmed previously in the program history. In this case, to make a move, both coordinates of the end point and the arc radius must be defined. To make a linear movement, program “G01”.
2. To make a circular movement (G02/G03), both coordinates of the end point and the arc radius must be programmed.

0044 ‘Incorrect Coordinates.’

**DETECTION**
During the execution in programs transmitted via DNC.

**CAUSE**
An attempt has been made to execute a block syntactically incorrect (G1 X20K-15)

**SOLUTION**
correct the syntax of the block.

0045 ‘Polar coordinates not allowed.’

**DETECTION**
While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE**
When “Programming with respect to home (G53)”, the end point has been defined in polar or cylindrical coordinates or in Cartesian coordinates with an angle.

**SOLUTION**
When programming with respect to home, only Cartesian coordinates may be programmed.

0046 ‘Axis does not exist.’

**DETECTION**
While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE**
A block has been edited whose execution involves the movement of a nonexistent axis.

**SOLUTION**
Check that the axis name being edited is correct.

0047 ‘Program axes.’

**DETECTION**
While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE**
No axis has been programmed in a function requiring an axis.

**SOLUTION**
Some instructions require the programming of axes (REPOS, G14, G20, G21...).
0048 ‘Incorrect order of axes.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE The axis coordinates have not been programmed in the correct order or an axis has
been programmed twice in the same block.
SOLUTION Remember that the correct programming order for the axes is:
X...Y...Z...U...V...W...A...B...C...
All axes need not be programmed.

0049 ‘Point incompatible with active plane.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE The possible causes are:
1. When trying to do a circular interpolation, the end point is not in the active plane.
2. When trying to do a tangential exit in a path that is not in the active plane.
SOLUTION The solution for each cause is:
1. Maybe a plane has been defined with “G16”, “G17”, “G18” or “G19”. In this case, circular
interpolations can only be carried out on the main axes defining that plane. To define a circular
interpolation in another plane, it must be defined beforehand.
2. Maybe a plane has been defined with “G16”, “G17”, “G18” or “G19”. In this case, corner
rounding, chamfers and tangential entries/exits can only be carried out on the main axes defining that plane. To do it in another plane, it must be defined beforehand.

0050 ‘Program positions on active plane.’

No explanation required.

0051 ‘Perpendicular axis included in active plane.’

No explanation required.

0052 ‘Center of circle programmed incorrectly.’

No explanation required.

0053 ‘Program pitch.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE In the "Electronic threading cycle (G33)" the parameter for the thread pitch is missing.
SOLUTION Remember that the programming format for this function is:
G33 X...C...L...
Where: “L” is the thread pitch.

0054 ‘Pitch programmed incorrectly.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE A helical interpolation has been programmed with the wrong or negative pitch.
SOLUTION Remember that the programming format is:
G02/G03 X...Y...I...J...Z...K...
Where: “K” is the helical pitch (always positive value).

0055 ‘Positioning axes or Hirth axes not allowed’

No explanation required.

0056 ‘The axis is already slaved.’

No explanation required.
**0057 ‘Do not program a slaved axis.’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The possible causes are:
1. When trying to move an axis alone while being slaved to another one.
2. When trying to slave an axis that is already slaved using the G77 function “Electronic axis slaving”.

**SOLUTION** The solution for each cause is:
1. A slaved axis cannot be moved separately. To move a slaved axis, its master axis must be moved. Both axes will move at the same time.
   Example: If the Y axis is slaved to the X axis, an X axis move must be programmed in order to move the Y axis (together with the X axis).
   To unslave the axes, program “G78”.
2. An axis cannot be slaved to two different axes at the same time. To unslave the axes, program “G78”.

---

**0058 ‘Do not program a GANTRY axis.’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The possible causes are:
1. When trying to move an axis alone while being slaved to another one as a GANTRY axis.
2. When defining an operation on a GANTRY axis. (Definition of work zone limits, planes, etc.).

**SOLUTION** The solution for each cause is:
1. A GANTRY axis cannot be moved separately. To move a GANTRY axis, its associated axis must be moved. Both axes will move at the same time.
   Example: If the Y axis is a GANTRY axis associated with the X axis, an X axis move must be programmed in order to move the Y axis (together with the X axis).
   GANTRY axes are defined by machine parameter.
2. The axes defined as GANTRY cannot be used in the definition of operations or movements. These operations are defined with the main axis that the GANTRY axis is associated with.

---

**0059 ‘The position programmed for the HIRTH axis is wrong’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** A rotation of a HIRTH axis has been programmed with a decimal value.

**SOLUTION** HIRTH axes do not accept decimal angular values. They must be full degrees.

---

**0060 ‘Invalid action.’**

No explanation required.

---

**0061 ‘ELSE not associated with IF’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** While editing in High level language, when editing the “ELSE” instruction without having previously programmed an “IF”.

**SOLUTION** Remember that the programming formats for these instructions are:
1. (IF (condition) <action1>)
2. (IF (condition) <action1> ELSE <action2>)
   If the condition is true, it executes the <action1>, otherwise, it executes <action2>.

---

**0062 ‘Program label N(0-99999999).’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** While programming in high level language, a block number out of the 0-99999999 range has been programmed in the “RPT” or “GOTO” instruction.

**SOLUTION** Remember that the programming format of these instructions is:
1. (RPT N(block number), N(block number))
2. (GOTO N(block number))
   The block number (label) must be between 0 and 99999999.
0063 ‘Program subroutine number 1 thru 9999.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE While programming in high level language, a subroutine number out of the 0-9999 range has been programmed in the “SUB” instruction.

SOLUTION Remember that the programming format for this instruction is:

\[(\text{SUB} \ (\text{integer}))\]

The subroutine number must be between 0 and 9999.

0064 ‘Repeated subroutine.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE There has been an attempt to define a subroutine already existing in another program of the memory.

SOLUTION In the CNC memory, there could not be more than one subroutine with the same identifying number even if they are contained in different programs.

0065 ‘The main program cannot have a subroutine.’

DETECTION In execution or while executing programs transmitted via DNC.

CAUSE The possible causes are:

1. An attempt has been made to define a subroutine in the MDI execution mode.
2. A subroutine has been defined in the main program.

SOLUTION The solution for each cause is:

1. Subroutines cannot be defined from the “MDI execution” option of the menu.
2. Subroutines must be defined after the main program or in a separate program. They cannot be defined before or inside the main program.

0066 ‘Expecting a message.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE While programming in high level, the “MSG” or “ERROR” instruction has been edited but without the message to be displayed.

SOLUTION Remember that the programming format of these instructions is:

\[(\text{MSG} \ “\text{message}”)\]
\[(\text{ERROR} \ \text{integer}, \ “\text{error message}”)]

Although it can also be programmed as follows:

\[(\text{ERROR} \ \text{integer})\]
\[(\text{ERROR} \ “\text{error message}”)\]

0067 ‘OPEN is missing.’

DETECTION In execution or while executing programs transmitted via DNC.

CAUSE While programming in high level, a “WRITE” instruction has been edited but the OPEN instruction has not been written previously to tell it where that instruction has to be executed.

SOLUTION The “OPEN” instruction must be edited before the “WRITE” instruction to “tell” the CNC where (in which program) it must execute the “WRITE” instruction.

0068 ‘Expecting a program number.’

No explanation required.

0069 ‘Program does not exist.’

DETECTION In execution or while executing programs transmitted via DNC.

CAUSE In the “Pattern repeat canned cycle (G66)”, “Roughing canned cycle along the X axis (G68)” or “Roughing canned cycle along the Z axis (G69)”, it has been programmed that the profiles are located in another program (parameter “Q”), but the program does not exist.

SOLUTION Parameter “Q” defines which program contains the profile definitions of the cycles. If this parameter is programmed, that program number must exist and it must contain the labels defined by parameters “S” and “E”.

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Ref. 1010
**0070 ‘Program already exists.’**

**DETECTION** In execution or while executing programs transmitted via DNC.

**CAUSE** This error comes up during execution when using the “OPEN” instruction (While programming in high level language) to create an already existing program.

**SOLUTION** Change the program number or use parameters A/D in the “OPEN” instruction:

(OPEN P........,A/D,... )

Where:
A: Appends new blocks after the existing ones.
D: Deletes the existing program and it opens it as a new one.

---

**0071 ‘Expecting a parameter’**

**DETECTION** While editing tables.

**CAUSE** The wrong parameter number has been entered (maybe the “P” character is missing) or another action is being carried out (moving around in the table) before quitting the table editing mode.

**SOLUTION** Enter the parameter number to be edited or press [ESC] to quit this mode.

---

**0072 ‘Parameter does not exist.’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** While programming in high level language, the “ERROR” instruction has been edited, but the error number to be displayed has been defined either with a local parameter greater than 25 or with a global parameter greater than 299.

**SOLUTION** The parameters used by the CNC are:

Local: 0-25
Global: 100-299

---

**0073 ‘Parameter range protected. Cannot be written.’**

No explanation required.

---

**0074 ‘Variable not accessible from CNC.’**

No explanation required.

---

**0075 ‘Read-only variable.’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** An attempt has been made to assign a value to a read-only variable.

**SOLUTION** Read-only variables cannot be assigned any values through programming. However, their values can be assigned to a parameter.

---

**0076 ‘Write-only variable.’**

No explanation required.

---

**0077 ‘Analog output not available.’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** An attempt has been made to write to an analog output currently being used by the CNC.

**SOLUTION** The selected analog output may be currently used by an axis or a spindle. Select another analog output between 1 and 8.

---

**0078 ‘Program channel 0(CNC),1(PLC) or 2(DNC).’**

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** While programming in high level language, the “KEYSCR” instruction has been programmed, but the source of the keys is missing.

**SOLUTION** When programming the “KEYSCR” instruction, the parameter for the source of the keys must always be programmed:

(KEYSCR=0) : CNC keyboard
(KEYSCR=1) : PLC
(KEYSCR=2) : DNC

The CNC only lets modifying the contents of this variable if it is "zero"
0079 ‘Program error number 0 thru 9999.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, the “ERROR” instruction has been programmed, but the error number to be displayed is missing.
SOLUTION Remember that the programming format for this instruction is:
    (ERROR integer, “error message”)  
Although it can also be programmed as follows:
    (ERROR integer)
    (ERROR “error message”)  

0080 ‘Operator missing.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, the “ERROR” instruction has been programmed, but the error number to be displayed is missing.
SOLUTION Remember that the programming format for this instruction is:
    (ERROR integer, “error message”)  
Although it can also be programmed as follows:
    (ERROR integer)
    (ERROR “error message”)  

0081 ‘Incorrect expression.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, an expression has been edited with the wrong format.
SOLUTION Correct the syntax of the block.

0082 ‘Incorrect operation.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE  
The possible causes are:
1. While programming in high level language, the assignment of a value to a parameter is incomplete.
2. While programming in high level language, the call to a subroutine is incomplete.
SOLUTION Correct (complete) the format to assign a value to a parameter or a call to a subroutine.

0083 ‘Incomplete operation.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, the “IF” instruction has been edited without the condition between brackets.
SOLUTION Remember that the programming formats for this instruction are:
    (IF (condition) <action1>)  
    (IF (condition) <action1> ELSE <action2>)  
If the condition is true, it executes the <action1>, otherwise, it executes <action2>.

0084 ‘Expecting “=”.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, a symbol or data has been entered that does not match the syntax of the block.
SOLUTION Enter the “=” symbol in the right place.

0085 ‘Expecting “)”.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, a symbol or data has been entered that does not match the syntax of the block.
SOLUTION Enter the “)” symbol in the right place.

0086 ‘Expecting “(”.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, a symbol or data has been entered that does not match the syntax of the block.
SOLUTION Enter the “(” symbol in the right place.
0087 'Expecting ",",' :

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE The possible causes are:
1. While programming in high level language, a symbol or data has been entered that does not match the syntax of the block.
2. While programming in high level language, an ISO-coded instruction has been programmed.
3. While programming in high level language, an operation has been assigned either to a local parameter greater than 25 or to a global parameter greater than 299.
SOLUTION The solution for each cause is:
1. Enter the "," symbol in the right place.
2. A block cannot contain high level language instructions and ISO-coded instructions at the same time.
3. The parameters used by the CNC are:
   Local: 0-25.
   Global: 100-299.
   Other parameters out of this range cannot be used in operations.

0088 'Operation limit exceeded.'

No explanation required.

0089 'Logarithm of zero or negative number.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An operation has been programmed which involves the calculation of a negative number or a zero.
SOLUTION Only logarithms of numbers greater than zero can be calculated. When working with parameters, that parameter may have already acquired a negative value or zero. Verify that the parameter does not reach the operation with that value (0).

0090 'Square root of a negative number.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An operation has been programmed which involves the calculation of the square root of a negative number.
SOLUTION Only the square root of numbers greater than zero can be calculated. When working with parameters, that parameter may have already acquired a negative value or zero. Verify that the parameter does not reach the operation with that value (0).

0091 'Division by zero.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An operation has been programmed whose execution involves dividing by zero.
SOLUTION It is only possible to divide by numbers other than zero. When working with parameters, that parameter may have already acquired a negative value or zero. Verify that the parameter does not reach the operation with that value (0).

0092 'Base zero with positive exponent.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An operation has been programmed which involves elevating zero to a negative exponent (or zero).
SOLUTION Zero can only be elevated to positive exponents greater than zero. When working with parameters, that parameter may have already acquired a negative value or zero. Check that the parameter does not reach the operation with that value.

0093 'Negative base with decimal exponent.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An operation has been programmed which involves elevating a negative number to a decimal exponent.
SOLUTION Negative numbers can only be elevated to integer exponents. When working with parameters, that parameter may have already acquired a negative value or zero. Check that the parameter does not reach the operation with that value.
0094  ‘ASIN/ACOS range exceeded.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An operation has been programmed which involves calculating the arcsine or
arccosine of a number out of the ±1 range.
SOLUTION Only the arcsine (ASIN) or arccosine (ACOS) of numbers between ±1 can be
 calculated. When working with parameters, that parameter may have already
 acquired a negative value or zero. Verify that the parameter does not reach the
 operation with that value (0).

0095  ‘Program row number.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While editing a customizing program, a window has been programmed with the
 “ODW” instruction, but the vertical position of the window on the screen is missing.
SOLUTION The vertical position of the window on the screen is defined by rows (0-25).

0096  ‘Program column number.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While editing a customizing program, a window has been programmed with the
 “ODW” instruction, but the horizontal position of the window on the screen is missing.
SOLUTION The horizontal position of the window on the screen is defined by columns (0-79).

0097  ‘Program another softkey.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While editing a customizing program, the programming format for the “SK” instruction
 has not been respected.
SOLUTION Correct the syntax of the block. The programming format is:
(SK1=(text 1), SK2=(text 2)...) If the “,” character is entered after a text, the CNC expects the name of another softkey.

0098  ‘Program softkeys 1 thru 7.’

DETECTION While executing in the user channel.
CAUSE In the block syntax, a softkey has been programmed out of the 1 to 7 range.
SOLUTION Only softkeys within the 1 to 7 range can be programmed.

0099  ‘Program another window.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While editing a customizing program, the programming format for the “DW” instruction
 has not been respected.
SOLUTION Correct the syntax of the block. The programming format is:
(DW1=(assignment), DW2=(assignment)...) If the “,” character is entered after an assignment, the CNC expects the name of another window.

0100  ‘Program windows 0 thru 25.’

DETECTION While executing in the user channel.
CAUSE In the block syntax, a window has been programmed out of the 0 to 25 range.
SOLUTION Only windows within the 0 to 25 range can be programmed.

0101  ‘Program rows 0 thru 20.’

DETECTION While executing in the user channel.
CAUSE In the block syntax, a row has been programmed out of the 0 to 20 range.
SOLUTION Only rows within the 0 to 20 range can be programmed.

0102  ‘Program columns 0 thru 79.’

DETECTION While executing in the user channel.
CAUSE In the block syntax, a column has been programmed out of the 0 to 79 range.
SOLUTION Only columns within the 0 to 79 range can be programmed.
0103 ‘Program pages 0 thru 255.’

DETECTION While executing in the user channel.
CAUSE In the block syntax, a page has been programmed out of the 0 to 255 range.
SOLUTION Only pages within the 0 to 255 range can be programmed.

0104 ‘Program INPUT.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, an “IB” instruction has been edited without associating an “INPUT” to it.
SOLUTION Remember that the programming formats for this instruction are:
   (IB (expression) = INPUT “text”, format)
   (IB (expression) = INPUT “text”)

0105 ‘Program inputs 0 thru 25.’

DETECTION While executing in the user channel.
CAUSE In the block syntax, an input has been programmed out of the 0 to 25 range.
SOLUTION Only inputs within the 0 to 25 range can be programmed.

0106 ‘Program numerical format.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, an “IB” instruction has been edited with non-numeric format.
SOLUTION Remember that the programming format for this instruction is:
   (IB (expression) = INPUT “text”, format)
Where “format” must be a signed number with 6 entire digits and 5 decimals at the most.
If the “*” character is entered after the text, the CNC expects the format.

0107 ‘Do not program formats greater than 6.5.’

DETECTION While executing in the user channel.
CAUSE While programming in high level language, an “IB” instruction has been edited in a format with more than 6 entire digits or more than 5 decimals.
SOLUTION Remember that the programming format for this instruction is:
   (IB (expression) = INPUT “text”, format)
Where “format” must be a signed number with 6 entire digits and 5 decimals at the most.

0108 ‘This command can only be executed in the user channel.’

DETECTION During execution.
CAUSE An attempt has been made to execute a block containing information that can only be executed through the user channel.
SOLUTION There are specific expressions for customizing programs that can only be executed inside the user program.

0109 ‘C. user: do not program geometric help, compensation or cycles.’

DETECTION While executing in the user channel.
CAUSE An attempt has been made to execute a block containing geometric aide, tool radius/length compensation or machining canned cycles.
SOLUTION Inside a customizing program the following cannot be programmed:
   - Neither geometric assistance nor movements.
   - Neither tool radius nor length compensation.
   - Canned cycles.

0110 ‘Local parameters not allowed.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE Some functions can only be programmed with global parameters.
SOLUTION Global parameters are the ones included in the 100-299 range.
0111 ‘Block cannot be executed while running another program’

DETECTION While executing in MDI mode.
CAUSE An attempt has been made to execute a customizing instruction from MDI mode while the user channel program is running.
SOLUTION Customizing instructions can only be executed through the user channel.

0112 ‘WBUF can only be executed in user channel while editing’

DETECTION During normal execution or execution through the user channel.
CAUSE An attempt has been made to execute the “WBUF” instruction.
SOLUTION The “WBUF” instruction cannot be executed. It can only be used in the editing stage through the user input.

0113 ‘Table limits exceeded.’

DETECTION While editing tables.
CAUSE The possible causes are:
1. In the tool offset table, an attempt has been made to define a tool offset with a greater number than allowed by the manufacturer.
2. In the parameter tables, an attempt has been made to define a nonexistent parameter.
SOLUTION The tool offset number must be smaller than the one allowed by the manufacturer.

0114 ‘Tool offset: D3 X Z R F I K.’

DETECTION While editing tables.
CAUSE In the tool offset table, the parameter editing order has not been respected.
SOLUTION Enter the table parameters in the right order.

0115 ‘Tool: T4 D3 F3 N5 R5(.2).’

DETECTION While editing tables.
CAUSE In the tool table, the parameter editing order has not been respected.
SOLUTION Enter the table parameters in the right order.

0116 ‘Origin: G54-59 G159N(1-20) axes(1-7).’

DETECTION While editing tables.
CAUSE In the Zero offset table, the zero offset to be defined (G54-G59) or G159N(1-20) has not been selected.
SOLUTION Enter the table parameters in the right order. To fill out the zero offset table, first select the offset to be defined (G54-G59) or G159N(1-20) and then the zero offset position for each axis.

0117 ‘M function: M4 S4 bits(8).’

DETECTION While editing tables.
CAUSE In the “M” function table, the parameter editing order has not been respected.
SOLUTION Edit table following the format:
M1234  (associated subroutine)   (customizing bits)

0118 ‘G51 [A] E’

DETECTION In execution or while executing programs transmitted via DNC.
CAUSE In the “Look-Ahead (G51)” function, the parameter for the maximum contouring error is missing.
SOLUTION This type of machining requires the programming of:
E : Maximum contouring error.
The rest of the parameters are optional. The parameters must be edited in the order indicated by the error message.

0119 ‘Leadscrew: Position-error.’

DETECTION While editing tables.
CAUSE In the leadscrew compensation tables, the parameter editing order has not been respected.
SOLUTION Enter the table parameters in the right order.
P123  (position of the axis to be compensated)   (leadscrew error at that point)
0120  ‘Incorrect axis.’

DETECTION While editing tables.
CAUSE In the leadscrew compensation tables, an attempt has been made to edit a different axis from the one corresponding to that table.
SOLUTION Each axis has its own table for leadscrew compensation. The table for each axis can only contain the positions for that axis.

0121  ‘Program P3 = value.’

DETECTION While editing tables.
CAUSE In the machine parameter table, the editing format has not been respected.
SOLUTION Enter the table parameters in the right order.
\[ P123 = \text{(parameter value)} \]

0122  ‘Magazine: P(1-255) = T(1-9999).’

DETECTION While editing tables.
CAUSE In the tool magazine table, the editing format has not been respected or some data is missing.
SOLUTION Enter the table parameters in the right order.

0123  ‘Tool T0 does not exist.’

DETECTION While editing tables.
CAUSE In the tool table, an attempt has been made to edit a tool as T0.
SOLUTION No tool can be edited as T0. The first tool must be T1.

0124  ‘Offset D0 does not exist.’

DETECTION While editing tables.
CAUSE In the tool table, an attempt has been made to edit a tool offset as D0.
SOLUTION No tool offset can be edited as D0. The first tool offset must be D1.

0125  ‘Do not modify the active tool or the next one.’

DETECTION During execution.
CAUSE In the tool magazine table, an attempt has been made to change the active tool or the next one.
SOLUTION During execution, neither the active tool nor the next one may be changed.

0126  ‘Tool not defined.’

DETECTION While editing tables.
CAUSE In the tool magazine table, an attempt has been made to assign to the magazine position a tool that is not defined in the tool table.
SOLUTION Define the tool in the tool table.

0127  ‘Magazine is not RANDOM.’

DETECTION While editing tables.
CAUSE There is no RANDOM magazine and, in the tool magazine table, the tool number does not match the tool magazine position.
SOLUTION When the tool magazine is not RANDOM, the tool number must be the same as the magazine position (pocket number).

0128  ‘The position of a special tool is set.’

DETECTION While editing tables.
CAUSE In the tool magazine table, an attempt has been made to place a tool in a magazine position reserved for a special tool.
SOLUTION When a special tool occupies more than one position in the magazine, it has a reserved position in the magazine. No other tool can be placed in this position.

0129  ‘Next tool only possible in machining centers.’

DETECTION During execution.
CAUSE A tool change has been programmed with M06, but the machine is not a machining center. (it is not expecting the next tool).
SOLUTION When the machining is not a machining center, the tool change is done automatically when programming the tool number “T”.
0130  ‘Write 0/1.’

DETECTION While editing machine parameters.
CAUSE An attempt has been made to assign the wrong value to a parameter.
SOLUTION The parameter only admits values of 0 or 1.

0131  ‘Write +/-:’

DETECTION While editing machine parameters.
CAUSE An attempt has been made to assign the wrong value to a parameter.
SOLUTION The parameter only admits values of + or -.

0132  ‘Write YES/NO:’

DETECTION While editing machine parameters.
CAUSE An attempt has been made to assign the wrong value to a parameter.
SOLUTION The parameter only admits values of YES or NO.

0133  ‘Write ON/OFF:’

DETECTION While editing machine parameters.
CAUSE An attempt has been made to assign the wrong value to a parameter.
SOLUTION The parameter only admits values of ON or OFF.

0134  ‘Values 0 thru 2:’
0135  ‘Values 0 thru 3:’
0136  ‘Values 0 thru 4:’
0137  ‘Values 0 thru 9:’
0138  ‘Values 0 thru 29:’
0139  ‘Values 0 thru 100:’
0140  ‘Values 0 thru 255:’
0141  ‘Values 0 thru 9999:’
0142  ‘Values 0 thru 32767:’
0143  ‘Values within +/-32767:’
0144  ‘Values 0 thru 65535:’

DETECTION While editing machine parameters.
CAUSE An attempt has been made to assign the wrong value to a parameter.
SOLUTION The parameter only admits values of:

1. An attempt has been made to assign the wrong value to a parameter.
2. During execution, when inside the program a call has been made to a subroutine (MCALL, PCALL) with a value greater than allowed.

0145  ‘Format +/- 5.5:’

DETECTION While editing machine parameters.
CAUSE An attempt has been made to assign the wrong value to a parameter.
SOLUTION The parameter only admits values with the format:

0146  ‘Word does not exist.’

No explanation required.

0147  ‘Numerical format exceeded.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE A data or parameter has been assigned a value greater than the established format.
SOLUTION Correct the syntax of the block. Most of the time, the numeric format will be 5.4 (5 integers and 4 decimals).

0148  ‘Text too long.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, the “ERROR” or “MSG” instruction has been assigned a text with more than 59 characters.
SOLUTION Correct the syntax of the block. The “ERROR” and “MSG” instructions cannot be assigned texts longer than 59 characters.
0149 ‘Incorrect message.’

- DETECTION: While editing at the CNC or while executing a program transmitted via DNC.
- CAUSE: While programming in high level language, the text associated with the “ERROR” or “MSG” instruction has been edited wrong.
- SOLUTION: Correct the syntax of the block. The programming format is:
  - (MSG “message”)
  - (ERROR number, “message”)
  The message must be between “ “.

0150 ‘Incorrect number of bits.’

- DETECTION: While editing tables.
- CAUSE: The possible causes are:
  1. In the "M" function table, in the section on customizing bits:
     - The number does not have 8 bits.
     - The number does not consist of 0's and 1's.
  2. In the machine parameter table, an attempt has been made to assign the wrong value of bit to a parameter.
- SOLUTION: The solution for each cause is:
  1. The customizing bits must consist of 8 digits of 0's and 1's.
  2. The parameter only admits 8-bit or 16-bit numbers.

0151 ‘Negative numbers not allowed.’

- No explanation required.

0152 ‘Incorrect parametric programming.’

- DETECTION: During execution.
- CAUSE: The parameter has a value that is incompatible with the function it has been assigned to.
- SOLUTION: This parameter may have taken the wrong value, in the program history. Correct the program so this parameter does not reach the function with that value.

0153 ‘Decimal format not allowed.’

- No explanation required.

0154 ‘Insufficient memory.’

- DETECTION: During execution.
- CAUSE: The CNC does not have enough memory to internally calculate the paths.
- SOLUTION: Sometimes, this error is taken care of by changing the machining conditions.

0155 ‘Help not available.’

- No explanation required.

0156 ‘Don’t program G33, G95 or M19 S with no spindle encoder’

- DETECTION: While editing at the CNC or while executing a program transmitted via DNC.
- CAUSE: A “G33”, “G95” or “M19 S” has been programmed without having an encoder on the spindle.
- SOLUTION: If the spindle does not have an encoder, functions “M19 S”, “G33” or “G95” cannot be programmed. Spindle machine parameter “NPULSES (P13)” indicates the number of encoder pulses per turn.

0159 ‘Inch programming limit exceeded.’

- DETECTION: During execution.
- CAUSE: An attempt has been made to execute in inches a program edited in millimeters.
- SOLUTION: Enter function G70 (inch programming) or G71 (mm programming) at the beginning of the program.

0162 ‘No negative radius allowed with absolute coordinates’

- DETECTION: During execution.
- CAUSE: While operating with absolute polar coordinates, a movement with a negative radius has been programmed.
- SOLUTION: Negative radius cannot be programmed when using absolute polar coordinates.
0164 'Wrong password.'

DETECTION While assigning protections.
CAUSE [ENTER] has been pressed before selecting the type of code to be assigned a password.
SOLUTION Use the softkeys to select the type of code to which a password is to be assigned.

0165 'Password: use uppercase/lowercase letters or digits.'

DETECTION While assigning protections.
CAUSE A bad character has been entered in the password.
SOLUTION The password can only consist of letters (upper and lower case) or digits.

0166 'Only one HIRTH axis per block is allowed.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE A movement has been programmed which involves the movement of two HIRTH axes simultaneously.
SOLUTION The CNC does not admit movements involving more than one HIRTH axis at a time. HIRTH axes must move one at a time.

0167 'Rot. axis position: absolute values (G90) within 0-359.9999.'

DETECTION During execution.
CAUSE A movement of a positioning-only rotary axis has been programmed. The movement has been programmed in absolute coordinates (G90) and the target coordinate of the movement is not within the 0 to 359.9999 range.
SOLUTION Positioning-only rotary axes: In absolute coordinates, only movements within the 0 to 359.9999 range are possible.

0168 'Rotary axis absolute values (G90) within ±359.9999.'

DETECTION During execution.
CAUSE A movement of a rotary axis has been programmed. The movement has been programmed in absolute coordinates (G90) and the target coordinate of the movement is not within the 0 to 359.9999 range.
SOLUTION Rotary axes: In absolute coordinates, only movements within the 0 to 359.9999 range are possible.

0169 'Modal subroutines cannot be programmed.'

DETECTION While executing in MDI mode.
CAUSE An attempt has been made to call upon a modal subroutine (MCALL).
SOLUTION MCALL modal subroutines cannot be executed from the menu option "MDI execution".

0170 'Program symbols 0 thru 255 in positions 0-639, 0-335.'

No explanation required.

0171 'The window must be previously defined.'

DETECTION During normal execution or execution through the user channel.
CAUSE An attempt has been made to write in a window (DW) that has not been previously defined (ODW).
SOLUTION It is not possible to write in a window that has not been previously defined. Check that the window to write in (DW) has been previously defined.

0172 'The program is not accessible.'

DETECTION During execution.
CAUSE An attempt has been made to execute a program that cannot be executed.
SOLUTION The program may be protected against execution. To know whether a program may be executed, check for the “X” character on the attributes column. If this character is missing, the program cannot be executed.

0173 'It is not possible to program angle-angle.'

No explanation required.
0174 ‘Circular (helical) interpolation not possible.’

DETECTION During execution.
CAUSE An attempt has been made to execute a helical interpolation while the "LOOK-AHEAD (G51)" function was active.
SOLUTION Helical interpolations are not possible while the "LOOK-AHEAD (G51)" function is active.

0175 'Analog inputs: ANA(1-8) = ±5 V.’

DETECTION During execution.
CAUSE An analog input has taken a value out of the ±5V range.
SOLUTION Analog inputs may only take values within the ±5V range.

0176 'Analog outputs: ANAO(1-8) = ±10 V’

DETECTION During execution.
CAUSE An analog output has been assigned a value out of the ±10V range.
SOLUTION Analog outputs may only take values within the ±10V range.

0177 'A gantry axis cannot be part of the active plane.’

No explanation required.

0178 ‘G96 only possible with analog spindle.’

DETECTION During execution.
CAUSE The “G96” function has been programmed but either the spindle speed is not controlled or the spindle does not have an encoder.
SOLUTION To operate with the “G96” function, the spindle speed must be controlled (SPDLTYPE(P0)=0) and the spindle must have an encoder (NPULSES(P13) other than zero).

0179 ‘Do not program more than 4 axes simultaneously.’

No explanation required.

0180 ‘Program DNC1/2E, HD or CARD A (optional).’

DETECTION While editing or executing.
CAUSE While programming in high level language, in the "OPEN" and "EXEC" instructions, an attempt has been made to program a parameter other than DNC1/2E, HD or CARD A, or the DNC parameter has been assigned a value other than 1, 2 or E.
SOLUTION Check the syntax of the block.

0181 ‘Program A (append) or D (delete).’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE In the "OPEN" instruction the A/D parameter is missing.
SOLUTION Check the syntax of the block. The programming format is:

(OPEN P.........,A/D,.... )

Where:

A Appends new blocks after the existing ones.
D Deletes the existing program and it opens it as a new one.

0182 ‘Option not available.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE A “G” function has been defined which is not a software option.

0184 ‘T with subroutine: Program only T and D.’

No explanation required.

0185 ‘Tool offset does not exist’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE Within the block syntax, a tool offset has been called upon which is greater than the ones allowed by the manufacturer.
SOLUTION Program a new smaller tool offset.
0186 ‘The “C” axis does not exist.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An attempt has been made to activate the “C” axis, but the machine does not have this feature.

0187 ‘G66, G68, G69 are not allowed when machining with the “C” axis.’

DETECTION During execution.
CAUSE An attempt has been made to execute a “G66”, “G68” or “G69” canned cycle while the “C” axis is active.
SOLUTION Cancel the “C” axis to work with these canned cycles.

0188 ‘Function not possible from PLC.’

DETECTION During execution.
CAUSE From the PLC channel and using the “CNCEX” instruction, an attempt has been made to execute a function that is incompatible with the PLC channel execution.
SOLUTION The installation manual (chapter 11.1.2) offers a list of the functions and instructions that may be executed through the PLC channel.

0189 ‘The live tool does not exist.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An attempt has been made to start the live tool “M45 S...”, but the machine does not have this feature.

0194 ‘Repositioning not allowed.’

DETECTION During execution.
CAUSE The axes cannot be repositioned using the “REPOS” instruction because the subroutine has not been activated with one of the interruption inputs.
SOLUTION Before executing the “REPOS” instruction, one of the interruption inputs must be activated.

0195 ‘Axes X, or Z slaved or synchronized.’

DETECTION During execution.
CAUSE While programming in high level language, an attempt has been made to execute a probing cycle using the “PROBE” instruction, but one of the X or Z axis is slaved or synchronized.
SOLUTION To execute the “PROBE” instruction, the X-Z axes must not be slaved or synchronized. To unslave the axes, program “G78”.

0196 ‘Axes X and Z must exist.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE While programming in high level language, an attempt has been made to edit the “PROBE” instruction, but one of the X or Z axis is missing.
SOLUTION To operate with the “PROBE” instruction, the X, Z axes must be defined.

0197 ‘G15 must be programmed before the “C” axis.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.
CAUSE An attempt has been made to execute an operation on the “C” axis, but the axis is not active.
SOLUTION In order to operate with the “C” axis, it must be activated first using the “G15” function.

0199 ‘Rotary axis preset: Value between 0 and -359.9999.’

DETECTION While presetting coordinates.
CAUSE An attempt has been made preset the coordinates of a rotary axis with a value out of the 0 to 359.9999 range.
SOLUTION The preset value of rotary axes must be within the 0 to 359.9999 range.
0200 ‘Program: G52 axis ±5.5’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE When programming the “Movement against a hard stop (G52)”, either the axis to be moved has not been programmed or several axes have been programmed.

SOLUTION When programming “G52”, the axis to be moved must be indicated. Only one axis may be programmed at a time.

0201 ‘Program only one positioning axis in G01’

No explanation required.

0206 ‘Values 0 thru 6.’

DETECTION While editing machine parameters.

CAUSE An attempt has been made to assign the wrong value to a parameter.

SOLUTION The parameter only admits values between 0 and 6.

0207 ‘Complete Table.’

DETECTION While editing tables.

CAUSE In the tables for “M” functions or tool offsets, an attempt has been made to define more data than those allowed by the manufacturer by means of machine parameters. When loading a table via DNC, the CNC does not delete the previous table, it replaces the existing values and it copies the new data in the free positions of the table.

SOLUTION The maximum number of data that can be defined is limited by the machine parameters:

- Maximum number of “M” functions: NMISCFUN(P29).
- Maximum number of tool offset: NTOFFSET(P27).
- Maximum number of magazine positions: NPOCKET(P25).

To load a new table via DNC, the previous table should be deleted.

0208 ‘Program A from 0 to 255’

DETECTION During execution.

CAUSE In the “LOOK-AHEAD (G51)” function, parameter “A” (% of acceleration to be applied) has been programmed with a value greater than 255.

SOLUTION Parameter “A” is optional, but when programmed, it must have a value between 0 and 255.

0209 ‘Program nesting not allowed.’

DETECTION During execution.

CAUSE From a running program, an attempt has been made to execute another program with the “EXEC” instruction which in turn also has an “EXEC” instruction.

SOLUTION Another program cannot be called upon from a program being executed using the “EXEC” instruction.

0210 ‘No compensation is permitted.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE An attempt has been made to activate or cancel tool radius compensation (G41, G42, G40) in a block containing a nonlinear movement.

SOLUTION Tool radius compensation must be activated/deactivated in linear movements (G00, G01).

0213 ‘A second spindle is required for G28, G29, G77 or G78.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE An attempt has been made to select the work spindle with “G28/G29” or synchronize spindles with “G77/G78”, but the machine only has one work spindle.

SOLUTION If the machine only has one work spindle, the “G28, G29, G77 and G78” functions cannot be programmed.
### 0214 ‘Invalid G function when selecting a profile’

**DETECTION** While restoring a profile.

**CAUSE** Within the group of blocks selected to restore the profile, there is a block containing a "G" code that does not belong in the profile definition.

**SOLUTION** The "G" functions available in the profile definition are:

- G00
- G01
- G02
- G03
- G06
- G08
- G09
- G36
- G37
- G38
- G39
- G90
- G91
- G93

### 0215 ‘Invalid G function after first point of profile’

**DETECTION** While restoring a profile.

**CAUSE** Within the selected blocks for restoring the profile, and after the starting point of a profile, there is a block containing a "G" function that does not belong in the profile definition.

**SOLUTION** The "G" functions available in the profile definition are:

- G00
- G01
- G02
- G03
- G06
- G08
- G09
- G36
- G37
- G38
- G39
- G90
- G91
- G93

### 0216 ‘Nonparametric assignment after first point of profile’

**DETECTION** While restoring a profile.

**CAUSE** Within the selected blocks for restoring the profile, and after the starting point of a profile, a nonparametric assignment has been programmed in high level language (a local or global parameter).

**SOLUTION** The only high level instructions that can be edited are assignments to local parameters (P0 thru P25) and global parameters (P100 thru P299).

### 0217 ‘Invalid programming after first point of profile’

**DETECTION** While restoring a profile.

**CAUSE** Within the selected blocks for restoring the profile, and after the starting point of a profile, there is a high level block that is not an assignment.

**SOLUTION** The only high level instructions that can be edited are assignments to local parameters (P0 thru P25) and global parameters (P100 thru P299).

### 0218 ‘The axis cannot be programmed after first point of profile’

**DETECTION** While restoring a profile.

**CAUSE** Within the selected blocks for restoring the profile, and after the starting point of a profile, a position has been defined on an axis that does not belong to the active plane. A surface coordinate may have been defined after the starting point of the profile.

**SOLUTION** The surface coordinate of the profiles is only defined in the starting block of the first profile, the one corresponding to the starting point of the outside profile.

### 0219 ‘First point programmed wrong when selecting profile’

**DETECTION** While selecting a profile.

**CAUSE** The starting point of the profile has been programmed wrong. One of the two coordinates defining its position is missing.

**SOLUTION** The starting point of a profile must be defined on the two axes forming the active plane.

### 0220 ‘Invalid axes’

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** The axes that have been defined are not valid for G46.

**SOLUTION** Check the following:

- G.m.p. ANGAXNA (P171) and g.m.p. ORTAXNA (P172) are other than 0.
- The defined axes exist and are linear.

### 0227 ‘Program Q between +/-359.9999.’

**DETECTION** While editing at the CNC or while executing a program transmitted via DNC.

**CAUSE** In the "Electronic threading (G33)" function, the entry angle “Q” has been programmed with a value out of the ±359.9999 range.

**SOLUTION** Program an entry angle within the ±359.9999 range.
0228  'Do not program "Q" with parameter M19TYPE=0.'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE In the "Electronic threading (G33)" function, an entry angle "Q" has been programmed, but the type of spindle orientation available does not allow this operation.

SOLUTION In order to define an entry angle, spindle machine parameter M19TYPE(P43) must be set to "1".

0229  'Program maximum Z'

0230  'Program inside R'

0231  'Program outside R'

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE In the "Electronic threading (G33)" function, an entry angle "Q" has been programmed, but the type of spindle orientation available does not allow this operation.

SOLUTION In order to define an entry angle, spindle machine parameter M19TYPE(P43) must be set to "1".

0234  'Wrong graphic limits'

DETECTION During execution.

CAUSE One of the lower limits defined with the "DGWZ" instruction is greater than its corresponding upper limit.

SOLUTION Program the upper limit of the graphics display area greater than the lower ones.

0235  'Do not program the axis in tangential control'

No explanation required.

0236  'Do not program the longitudinal axis or the axis of the active plane'

No explanation required.

0237  'Program values between +/-359.9999.'

DETECTION During execution.

CAUSE A G30 offset has been programmed greater than the maximum allowed. For example G30 D380

SOLUTION The offset must be within ±359.9999.

0238  'Do not program G30 without synchronizing the spindles in speed'

DETECTION During execution.

CAUSE An attempt has been made to synchronize the spindles in "G30" offset without having them synchronized in speed.

SOLUTION First, synchronize the spindle in speed using G77S.

0239  'Do not synchronize the spindles while the "C" axis is active'

DETECTION During execution.

CAUSE An attempt has been made to synchronize the spindle, but the "C" axis is not active.

SOLUTION Activate the "C" axis first.

0240  'Do not activate the "C" axis while the spindles are synchronized'

DETECTION During execution.

CAUSE An attempt has been made to activate the "C" axis while the spindles were synchronized.

SOLUTION First, cancel the spindle synchronization (G78 S).

0241  'Do not program G77 S, G78 S with no spindle encoder'

DETECTION During execution.

CAUSE An attempt has been made to synchronize the spindles (G77 S or G78 S) and one of them does not have an encoder or Sercos feedback.

SOLUTION Both spindles must have an encoder or Sercos feedback.
0242 ‘Do not synchronize spindles with M19TYPE=0’

DETECTION During execution.

CAUSE An attempt has been made to synchronize the spindles (G77 S or G78 S) and one of them has parameter M19TYPE=0.

SOLUTION Both spindles must have parameter M19TYPE=1.

0243 ‘Values 0 thru 15.’
0244 ‘Values 0.00% thru 100.00%.’
0245 ‘Values -100.00% thru 100.00%.’

No explanation required.

0246 ‘Feedrate F cannot be negative or 0.’

DETECTION While editing at the CNC or while executing a program transmitted via DNC.

CAUSE If g.m.p. FEEDTYPE (P170) has a value other than ·0·, F0 cannot be programmed.

SOLUTION The possible solutions are:
• Set g.m.p. FEEDTYPE (P170) = 0.
  In this case the motion blocks are executed at the maximum feedrate allowed.
• Program F with a value other than ·0·.

0247 ‘Values 0 thru 8.’

No explanation required.
BLOCK PREPARATION AND EXECUTION ERRORS

1000 ‘There is no enough path information.’

| DETECTION  | During execution. |
| CAUSE      | The program contains too many blocks without information about the path to apply tool radius compensation, rounding, chamfer or tangential entry or exit. |
| SOLUTION   | In order to carry out these operations, the CNC needs to know in advance the path to follow; therefore, there cannot be more than 48 blocks in a row without information about the path to follow. |

1001 ‘Plane change in rounding/chamfering.’

| DETECTION  | During execution. |
| CAUSE      | A plane change has been programmed on the path following the definition of a “controlled corner rounding G36” or “chamfer (G39)”. |
| SOLUTION   | The plane cannot be changed while executing a rounding or a chamfer. The path following the definition of a rounding or chamfer must be in the same plane that the rounding or the chamfer. |

1002 ‘Rounding radius too large.’

| DETECTION  | During execution. |
| CAUSE      | In the “Controlled corner rounding (G36)” function, the programmed rounding radius is larger than one of the paths where it has been defined. |
| SOLUTION   | The rounding radius must be smaller than the paths that define it. |

1003 ‘Rounding in last block.’

| DETECTION  | During execution. |
| CAUSE      | A “Controlled rounding radius (G36)” or “Chamfer (G39) has been defined on the last path of the program or when the CNC does not find information about the path following the definition of the rounding or chamfer. |
| SOLUTION   | A rounding or chamfer must be defined between two paths. |

1004 ‘Tangential output programmed wrong’

| DETECTION  | During execution. |
| CAUSE      | The move following the definition of a tangential output (G38) is a circular path. |
| SOLUTION   | The move following the definition of a tangential output must be a straight path. |

1005 ‘Chamfer programmed wrong.’

| DETECTION  | During execution. |
| CAUSE      | The move following the definition of a “Chamfer (G39)” is a circular path. |
| SOLUTION   | The move following the definition of a chamfer must be a straight path. |

1006 ‘Chamfer value too large.’

| DETECTION  | During execution. |
| CAUSE      | In the “Chamfer (G39)” function, the programmed chamfer value is larger than one of the paths where it has been defined. |
| SOLUTION   | The chamfer size must be smaller than the paths that define it. |
1007 'G8 defined wrong.'

**DETECTION** During execution.

**CAUSE** The possible causes are:
1. When a full circle has been programmed using the function "Arc tangent to previous path (G08)"
2. When the tangent path ends in a point of the previous path or its extension (in a straight line).
3. In an irregular pocket canned cycle with islands, when programming function "G08" in the block following the definition of the beginning of the profile (G00).

**SOLUTION** The solution for each cause is:
1. Function "G08" does not allow programming full circles.
2. Tangent path must not end in a point of the previous path or in its extension (in a straight line).
3. The CNC does not have information about the previous path and cannot execute the tangent arc.

1008 'There is no information about the previous path'

**DETECTION** During execution.

**CAUSE** An arc tangent to the previous path has been programmed using function “G08”, but there is no information about the previous path.

**SOLUTION** To do a path tangent to the previous one, there must be information about the previous path and it must be within the 48 blocks preceding the tangent path.

1010 'Wrong plane for tangent path.'

**DETECTION** During execution.

**CAUSE** A plane change has been programmed between the definition of the function “arc tangent to previous path (G08)” and the previous path.

**SOLUTION** A plane cannot be changed between two paths.

1011 'No radius has been programmed for G15.'

**DETECTION** During execution.

**CAUSE** The Z-C plane has been selected as a new work plane, but the radius of the cylinder to be machined has not been defined.

**SOLUTION** In order to work in the Z-C plane, first define the radius of the cylinder on which to machine using function “G15 R...”

1015 'The tool is not defined in the tool table'

**DETECTION** During execution.

**CAUSE** A tool change has been defined, but the new tool is not defined in the tool table.

**SOLUTION** Define the new tool in the tool table.

1016 'The tool is not in the tool magazine'

**DETECTION** During execution.

**CAUSE** A tool change has been defined, but the new tool is not defined in position of the tool magazine table.

**SOLUTION** Define the new tool in the tool magazine table.

1017 'There is no empty pocket in the tool magazine'

**DETECTION** During execution.

**CAUSE** A tool change has been defined and there is no empty pocket for the tool that is currently in the spindle.

**SOLUTION** Perhaps, the new tool has been defined as special in the tool table and there are more than one pockets reserved to it in the magazine. In this case, that position is set for that tool and no other tool can occupy it. To avoid this error, an empty pocket (position) should be left in the tool magazine.
### 1018 ‘A tool change has been programmed without M06’

| DETECTION | During execution. |
| CAUSE     | An M06 has not been programmed after having looked for a tool and before searching again. |
| SOLUTION  | This error occurs when having a machining center (general machine parameter TOFFM06(P28)=YES) that has a cyclic tool changer (general machine parameter CYCATC(P61)=YES). In this case, the tool change must be done with an m06 after searching for a tool and before searching for the next one. |

### 1019 ‘There is no tool of the same family for replacement.’

| DETECTION | During execution. |
| CAUSE     | The real life of the requested tool exceeds its nominal life. The CNC has tried to replace it with another one of the same family, but it has not found any. |
| SOLUTION  | Replace the tool or define another one of the same family. |

### 1020 ‘Do not change the active or pending tool using high level language.’

| DETECTION | During execution. |
| CAUSE     | While programming in high level language and using the “TMZT” variable, an attempt has been made to assign the current or next tool to a magazine position. |
| SOLUTION  | Use the “T” function to change the active tool or the next one. The “TMZT” variable cannot be used to move the active tool or the next one to the magazine. |

### 1021 ‘No tool offset has been programmed in the canned cycle.’

| DETECTION | During execution. |
| CAUSE     | The “PROBE” canned cycle for tool calibration has been programmed, but no tool offset has been selected. |
| SOLUTION  | To execute the “Tool calibration canned cycle (PROBE), a tool offset must be selected where the probing cycle information will be stored. |

### 1022 ‘Tool radius programmed incorrectly’

| DETECTION | During execution. |
| CAUSE     | During execution. |
| SOLUTION  | No explanation required. |

### 1028 ‘Do not switch axes over or back while G15 is active’

| DETECTION | During execution. |
| CAUSE     | An attempt has been made to switch over to an axis or back (G28/G29) while function “G15” was active. |

### 1029 ‘Do not swap axes that are already swapped.’

| DETECTION | During execution. |
| CAUSE     | An attempt has been made to swap (G28) an axis that was already swapped with another one. |
| SOLUTION  | An axis already swapped with another one cannot be swapped with a third one. It must be switched back first (G29 axis). |

### 1030 ‘The “M” for the automatic gear change does not fit’

| DETECTION | During execution. |
| CAUSE     | Using automatic gear change, 7 “M” functions and the “S” function (involving a gear change) have been programmed. In this case, the CNC cannot include the “M” for automatic gear change in that block. |
| SOLUTION  | Program an “M” function or the “S” function in a separate block. |

### 1031 ‘No subroutine is allowed with automatic gear change.’

| DETECTION | During execution. |
| CAUSE     | On machines having an automatic gear change, when programming a spindle speed “S” that involves a gear change and the “M” function of the automatic gear change has a subroutine associated with it. |
| SOLUTION  | When having an automatic gear change, the “M” functions corresponding to the gear change cannot have a subroutine associated with it. |
### 1032 ‘Spindle gear not defined in M19.’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>“M19” has been programmed, but none of the gear change functions “M41”, “M42”, “M43” or “M44” are active.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>On power-up, the CNC does not assume any gear; Therefore, if the gear change function is not generated automatically (spindle parameter AUTOGEAR(P6)=NO), the auxiliary gear change functions (“M41”, “M42”, “M43” or “M44”) must be programmed.</td>
</tr>
</tbody>
</table>

### 1033 ‘Wrong gear change.’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>The possible causes are:</td>
</tr>
<tr>
<td></td>
<td>1. When trying to make a gear change and the machine parameters for gears (MAXGEAR1, MAXGEAR2, MAXGEAR3, or MAXGEAR4) are set wrong. All the gears have not been used and the unused ones have been set to a maximum speed of zero rpm.</td>
</tr>
<tr>
<td></td>
<td>2. When programming a gear change (“M41”, “M42”, “M43” or “M44”) and the PLC has not responded with the relevant active gear signal (GEAR1, GEAR2, GEAR3 or GEAR4).</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>The solution for each cause is:</td>
</tr>
<tr>
<td></td>
<td>1. When not using all four gears, the lower ones must be used starting with “MAXGEAR1” and the unused gears must be assigned the value of the highest one used.</td>
</tr>
<tr>
<td></td>
<td>2. Check the PLC program.</td>
</tr>
</tbody>
</table>

### 1034 ‘“S” has been programmed, but no gear is active.’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>An attempt has been made to start the spindle, but no gear is selected.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>On power-up, the CNC does not assume any gear; Therefore, when programming a spindle speed and the gear change function is not generated automatically (spindle parameter AUTOGEAR(P6)=NO), the auxiliary gear change functions (“M41”, “M42”, “M43” or “M44”) must be programmed.</td>
</tr>
</tbody>
</table>

### 1035 ‘Programmed “S” too high’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>An “S” has been programmed with a higher value than allowed by the last active gear.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Program a lower spindle speed “S” .</td>
</tr>
</tbody>
</table>

### 1036 ‘“S” has not been programmed in G95 or in threading’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>“mm(inches)/revolution (G95)” or “electronic threading (G33)” has been programmed, but no spindle speed has been selected.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>An “S” must be programmed to work in mm/rev (G95) or for an electronic threading (G33).</td>
</tr>
</tbody>
</table>

### 1037 ‘No “S” has been programmed for G96.’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>The “Constant Surface Speed (G96)” function has been programmed, but no cutting speed has been defined, a previous one does not exist or no spindle gear is selected.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>In order to work at constant surface speed (G96), a cutting speed “S” must be already programmed and a spindle gear must be active.</td>
</tr>
</tbody>
</table>

### 1038 ‘The spindle has not been oriented’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>An attempt has been made to execute a threading cycle (G86 or G87) as a thread repair without already having oriented the active spindle (main or secondary).</td>
</tr>
</tbody>
</table>
### 1039 ‘No “F” has been programmed in G94.’

| DETECTION | During execution. |
| CAUSE | An attempt has been made to execute a live tool cycle (G60, G61, G62 and G63) and there is feedrate selected in G94 (mm/min). |
| SOLUTION | First, select the feedrate “F” in mm/min (G94). |

### 1040 ‘Canned cycle does not exist’

| DETECTION | While executing in MDI mode |
| CAUSE | When trying to execute a canned cycle (G8x) after interrupting a program during the execution of a canned cycle (G8x) and then changing the plane. |
| SOLUTION | Do not interrupt the program while executing a canned cycle. |

### 1042 ‘Wrong parameter value in canned cycle’

| DETECTION | During execution. |
| CAUSE | When defining a canned cycle, a parameter has been defined with the wrong value. Perhaps, a parameter that only takes positive values has been assigned a negative value (or zero). |
| SOLUTION | Correct the definition of parameters:  
  - In the “Pattern repeat cycle”:  
    - Parameter “C” only takes positive values greater than zero.  
    - Parameter “A” only admits values of 0 or 1.  
    - Parameter “J” only takes positive values greater than zero.  
  - In the canned cycle for “roughing along the Z axis” or “roughing along the X axis”, parameter “C” only takes positive values greater than zero.  
  - In the “Axial drilling/tapping canned cycle”:  
    - Parameter “T” only admits values other than zero.  
    - Parameter “B” only takes positive values or zero.  
  - In the canned cycle for “facing curved sections” or “turning curved sections”, parameter “C” only takes positive values greater than zero.  
  - In the “Face threading canned cycle” or “Longitudinal threading canned cycle”, parameter “I”, “B”, “E” or “C” has been defined with a zero value.  
  - In the canned cycle for “grooving along the Z axis” or “grooving along the X axis”, parameter “C” only takes positive values greater than zero.  
  - In the canned cycle for “Face drilling/tapping” or “Longitudinal drilling/tapping”:  
    - Parameter “I” only admits values other than zero.  
    - Parameter “B” only takes positive values or zero.  
    - Parameter “J” only takes positive values greater than zero.  
  - In the canned cycle for “slot milling on the face” or “slot milling on the side”, the slot dimension cannot be zero and parameters “I” and “J” only take positive values greater than zero. |

### 1043 ‘Wrong tool for programmed profile.’

| DETECTION | During execution. |
| CAUSE | The selected tool cannot machine anywhere on the profile. |
| SOLUTION | Choose a more appropriate tool to machine the profile. |

### 1044 ‘A profile has been programmed that intersects itself.’

| DETECTION | During execution. |
| CAUSE | In the set of profiles, there is one that intersects itself. |
| SOLUTION | Check the definition of the profiles. A profile cannot intersect itself. |

### 1045 ‘Wrong cutter geometry angle.’

| DETECTION | During execution. |
| CAUSE | The cutter’s geometry angles have been assigned a wrong value. |
| SOLUTION | Correct the tool geometry data. |

### 1046 ‘Wrong tool position before the canned cycle’

| DETECTION | During execution. |
| CAUSE | The canned cycle calling point is defined wrong.  
The canned cycle calling point must be off the part and at a distance greater than the one defined as finishing stock on both axes. (Cycles that do not have a finishing stock will use the safety distance). |
1047 ‘Wrong location code in canned cycle’
DETECTION During execution.
CAUSE The location code (shape) of the tool is not the right one.
SOLUTION Choose a tool with the right location code (shape).

1048 ‘Wrong cutter width’
DETECTION During execution.
CAUSE A grooving operation has been defined with a cutter of zero width.
SOLUTION Check the definition of the cutter dimensions (NOSEW). The cutter width must be other than zero.

1049 ‘Incompatible tool position and location code in profile cycle.
DETECTION During execution.
CAUSE The canned cycle calling point is defined wrong or the tool location code (shape) is the right one to execute the machining operation.
SOLUTION The canned cycle calling point must be off the part and at a distance greater than the one defined as finishing stock on both axes. Besides, the tool's location code must allow executing the profile without running into the part.

1050 ‘Wrong value to be assigned to a variable’
DETECTION During execution.
CAUSE Using parameters, the value assigned to a variable is too high.
SOLUTION Check the program history to make sure that this parameter does not have that value when it reaches the block where this assignment is made.

1051 ‘Wrong access to PLC variable.’
DETECTION During execution.
CAUSE From the CNC, an attempt has been made to read a PLC variable that is not defined in the PLC program.

1052 ‘Access to a variable with wrong index’
DETECTION During editing.
CAUSE While programming in high level language, an operation has been carried out either with a local parameter greater than 25 or with a global parameter greater 299.
SOLUTION The parameters used by the CNC are:
- Local: 0-25.
- Global: 100-299.
Other parameters out of these ranges cannot be used in operations.

1053 ‘Local parameters not accessible’
DETECTION During execution.
CAUSE An attempt has been made to execute a block with an operation that uses local parameters.
SOLUTION The program that is executed in the user channel does not allow operations with local parameters (P0 to P25).

1054 ‘Limit of local parameters exceeded’
DETECTION During execution.
CAUSE While programming in high level language, more than 6 nesting levels have been used with the “PCALL” instruction. More than 6 calls have been made in the same loop using the “PCALL” instruction.
SOLUTION Only up to 6 nesting levels are allowed for local parameters within the 15 nesting levels of the subroutines. Calling with a “PCALL” instruction generates a new nesting level for local parameters (and a new one for subroutines).
**1055 ‘Nesting exceeded’**

| DETECTION | During execution. |
| CAUSE | While programming in high level language, more than 15 nesting levels have been used with the “CALL”, “PCALL” or “MCALL” instruction. More than 15 calls have been made in the same loop using the “CALL”, “PCALL” or “MCALL” instruction. |
| SOLUTION | Only 15 nesting levels allowed. Calling with the “CALL”, “PCALL” and “MCALL” instructions generates a new nesting level. |

**1056 ‘RET not associated with subroutine.’**

| DETECTION | During execution. |
| CAUSE | The “RET” instruction has been edited, but the “SUB” instruction has not been edited before. |
| SOLUTION | To using the “RET” instruction (subroutine), the subroutine must begin with the “SUB (subroutine number)”. |

**1057 ‘Undefined subroutine’**

| DETECTION | During execution. |
| CAUSE | A (CALL, PCALL...) has been made to a subroutine that was not defined in the CNC memory. |
| SOLUTION | Check that the name of the subroutine is correct and that the subroutine exists in the CNC memory (not necessarily in the same program where the call is). |

**1058 ‘Undefined probing canned cycle’**

| DETECTION | During execution. |
| CAUSE | Using the “PROBE” instruction, a probing cycle has been defined which is not available. |
| SOLUTION | The available “PROBE” canned cycles are 1 to 4. |

**1059 ‘Jump to an undefined label’**

| DETECTION | During execution. |
| CAUSE | While programming in high level language, the “GOTO N...” instruction has been programmed, but the programmed block number (N) does not exist. |
| SOLUTION | When programming the “GOTO N...” instruction, the block it refers to must be defined in the same program. |

**1060 ‘Undefined label’**

| DETECTION | During execution. |
| CAUSE | The possible causes are: |
| | 1. While programming in high level language, the instrucción “RPT N..., N...” instruction has been programmed, but a programmed block number (N) does not exist. |
| | 2. In the “Pattern repeat canned cycle (G66)”, “Roughing canned cycle along the X axis (G68)” or “Roughing canned cycle along the Z axis (G69)” a profile definition has been programmed, but one of the two data defining the beginning “S” or end “E” of the profiles is missing. |
| SOLUTION | The solution for each cause is: |
| | 1. When programming the “RPT N..., N...” instruction, the blocks it refers to must be defined in the same program. |
| | 2. Check the program. Place the label for parameter “S” at the beginning of the profile definition and the label for parameter “E” at the end of the profile definition. |

**1061 ‘Label cannot be searched’**

| DETECTION | While executing in MDI mode |
| CAUSE | While programming in high level language, either an “RPT N..., N...” or “GOTO N...” instruction has been defined. |
| SOLUTION | While operating in MDI mode, “RPT” or “GOTO” type instructions cannot be programmed. |
1062 'Subroutine in an unavailable program.'

| DETECTION | During execution. |
| CAUSE | A call has been made to a subroutine that it is located in a program being used by the DNC. |
| SOLUTION | Wait for the DNC to finish using the program. If the subroutine is to be used often, it should be stored in a separate program. |

1063 'The program cannot be opened.'

| DETECTION | During execution. |
| CAUSE | While executing a program in infinite mode, an attempt has been made to execute another infinite program from the current one using the "EXEC" instruction. |
| SOLUTION | Only one infinite program may be executed at a time. |

1064 'The program cannot be executed'

| DETECTION | During execution. |
| CAUSE | An attempt has been made to execute a program from another with the "EXEC" instruction, but the program does not exist or is protected against execution. |
| SOLUTION | The program to be executed with the "EXEC" instruction must exist in the CNC memory and must be executable. |

1065 'Beginning of compensation without straight path'

| DETECTION | During execution. |
| CAUSE | The first movement in work plane after activating tool radius compensation (G41/G42) is not a linear movement. |
| SOLUTION | The first movement after activating radius compensation (G41/G42) must be linear. |

1066 'End of compensation without straight path'

| DETECTION | During execution. |
| CAUSE | The first movement in work plane after deactivating tool radius compensation (G40) is not a linear movement. |
| SOLUTION | The first movement after deactivating radius compensation (G40) must be linear. |

1067 'Compensation radius too large.'

| DETECTION | During execution. |
| CAUSE | While working with tool radius compensation (G41/G42), an inside radius has been programmed with a smaller radius than that of the tool. |
| SOLUTION | Use a tool with a smaller radius. When working with tool radius compensation, the arc radius must larger than that of the tool. Otherwise, the tool cannot machine the programmed path. |

1068 'Step on linear path'

| DETECTION | During execution. |
| CAUSE | When operating with tool compensation (G41/G42), the profile has a straight section that cannot be machined because the tool diameter is too large. |
| SOLUTION | Use a tool with a smaller radius. |

1069 'Circular path defined incorrectly'

No explanation required.

1070 'Step on circular path'

| DETECTION | During execution. |
| CAUSE | When operating with tool compensation (G41/G42), the profile has a curved section that cannot be machined because the tool diameter is too large. |
| SOLUTION | Use a tool with a smaller radius. |

1071 'Plane change in tool radius compensation.'

| DETECTION | During execution. |
| CAUSE | When operating with tool compensation (G41/G42), another work plane has been selected. |
| SOLUTION | To change the work plane, tool radius compensation must be off (G40). |
1072 ‘Tool radius compensation not possible with positioning-only rotary axis.’

**DETECTION**
During execution.

**CAUSE**
An attempt has been made to move a positioning-only axis with tool radius compensation (G41/G42).

**SOLUTION**
Tool radius compensation not allowed for positioning-only rotary axes. Use “G40” to cancel tool radius compensation.

1073 ‘Motion block with zero speed.’

**DETECTION**
During execution.

**CAUSE**
If g.m.p. FEEDTYPE (P170) has a value other than -0-, F0 cannot be programmed.

**SOLUTION**
The possible solutions are:
- Set g.m.p. FEEDTYPE (P170) = 0.
  In this case the motion blocks are executed at the maximum feedrate allowed.
- Program F with a value other than -0-.

1075 ‘G51 is incompatible helical path.’

**DETECTION**
During execution.

**CAUSE**
A helical path has been executed while function G51 was active.

**SOLUTION**
Cancel G51 before executing the helical path.

1076 ‘Coordinate angle programmed wrong.’

**DETECTION**
During execution.

**CAUSE**
When programming in angle-coordinate format, an axis movement has been programmed with an angle perpendicular to that axis. (For example, the main plane is formed by the XZ axes and the X axis movement is programmed at a 90º angle).

**SOLUTION**
Check and correct the definition of the movement in the program. If using parameters, check that the parameters have the correct values when arriving to the definition of the movement.

1077 ‘Either the arc radius is too small or a full circle has been programmed’

**DETECTION**
During execution.

**CAUSE**
The possible causes are:
1. When programming a full circle using the “G02/G03 X Z R” format.
2. When programming using the “G02/G03 X Z R” format, the distance to the arc’s end point is greater than the diameter of the programmed circle.

**SOLUTION**
The solution for each cause is:
1. This format cannot be used to make full circles. Program the coordinates of the end point different from those of the starting point.
2. The diameter of the circle must be larger than the distance to the arc’s end point.

1078 ‘Negative radius in polar coordinates’

**DETECTION**
During execution.

**CAUSE**
Working with incremental polar coordinates, a block is executed where the end position has a negative radius.

**SOLUTION**
Incremental polar coordinate programming allows negative radius, but the (absolute) end point of the radius must be positive.

G74 ‘There is no subroutine associated with G74’

**DETECTION**
While executing a home search.

**CAUSE**
The possible causes are:
1. When trying to search home on all the axes manually, but there is no associated subroutine indicating the home searching sequence (order).
2. “G74” has been programmed, but there is no associated subroutine indicating the home searching sequence (order).

**SOLUTION**
The solution for each cause is:
1. An associated subroutine is required to execute the “G74” function.
2. If “G74” is to be executed from a program, the home searching order must be defined.
1080 'Plane change in tool inspection'

**DETECTION**
While executing the “tool inspection” option.

**CAUSE**
the work plane has been changed and the original one has not been restored before resuming the execution.

**SOLUTION**
The plane that was active before inspecting the tool must be restored before resuming the execution.

1081 'Block not allowed in tool inspection.'

**DETECTION**
While executing the “tool inspection” option.

**CAUSE**
An attempt has been made to execute the “RET” instruction.

**SOLUTION**
This instruction cannot be executed in the “tool inspection” option.

1082 'The probe signal has not been received.'

**DETECTION**
During execution.

**CAUSE**
The possible causes are:
1. When programming a “PROBE” canned cycle, the probe has moved the maximum safety distance of the cycle without the CNC receiving the probe signal.
2. When programming the “G75” function, it has reached the end point and the CNC has not received the signal from the probe. (Only when general machine parameter PROBERR(P119)=YES).

**SOLUTION**
The solution for each cause is:
1. Check that the probe is connected properly.
   The maximum probing distance (in PROBE cycles) depends on the safety distance “B”. To increase this distance, increase the safety distance.
2. If PROBERR(P119)=NO, this error will not be issued when the end point is reached without having received the probe signal (only with “G75”).

1083 'Range exceeded'

**DETECTION**
During execution.

**CAUSE**
The distance for the axes to travel is very long and the programmed feedrate is too low.

**SOLUTION**
Program a higher speed for that movement.

1084 'Arc programmed wrong'

**DETECTION**
During execution.

**CAUSE**
The possible causes are:
1. When the arc programmed using “G02/G03 X Y I J” cannot go through the defined end point.
2. When programming an arc using “G09 X Y I J” the three points are in line or two of them are the same.
3. When trying to do a rounding tangential entry on a path that is not in the active plane.
4. When programming a tangential exit and the next path is tangent (being on its straight extension) to the path preceding the tangential exit.
   If the error comes up in the block calling upon the “Pattern repeat canned cycle (G66)”, “Roughing canned cycle along X (G68)” or “Roughing canned cycle along Z (G69)” is because in the set of blocks that define the profiles, one of the cases mentioned earlier occurs.

**SOLUTION**
The solution for each cause is:
1. Correct the syntax of the block. The coordinates of the end point or of the radius are defined wrong.
2. The three points used to define an arc must be different and cannot be in line.
3. Maybe a plane has been defined with “G16”, “G17”, “G18” or “G19”. In this case, corner rounding, chamfers and tangential entries/exits can only be carried out on the main axes defining that plane. To do it in another plane, it must be defined beforehand.
4. The path after a tangential exit may be tangent, but it cannot be on the extension (in a straight line) of the previous path.
**1085 ‘Helical path programmed wrong’**

**DETECTION**
During execution.

**CAUSE**
When programming an arc using “G02/G03 X Y I J Z K”, the programmed arc is impossible. The desired height cannot be reached with the programmed helical pitch.

**SOLUTION**
Correct the syntax of the block. The height of the interpolation and the coordinates of the end point in the plane must be related taking the helical pitch into account.

**1086 ‘The spindle cannot be homed.’**

**CAUSE**
Spindle machine parameter REFEED1(P34) = 0.

**1087 ‘Circle with zero radius’**

**DETECTION**
During execution.

**CAUSE**
The possible causes are:
1. When programming an arc using “G02/G03 X Z I K”, an arc has been programmed with a zero radius.
2. When operating with tool radius compensation, an inside arc has been programmed with the same radius as that of the tool.

**SOLUTION**
The solution for each cause is:
1. Arcs with zero radius are not allowed. Program a radius other than zero.
2. When working with tool radius compensation, the arc radius must larger than that of the tool. Otherwise, the tool cannot machine the programmed path (because to do so, the tool would have to make an arc of zero radius).

**1088 ‘Range exceeded in zero offset.’**

**DETECTION**
During execution.

**CAUSE**
A zero offset has been programmed and the value of the end position is too high.

**SOLUTION**
Check that the values assigned to the zero offsets (G54-G59) are correct. If the zero offsets have been assigned values from the program using parameters, check that the parameter values are correct. If an absolute (G54-G57) and an incremental (G58-G59) zero offset has been programmed, check that the sum of both does not exceed the machine limits.

**1089 ‘Range exceeded in zone limit.’**

**DETECTION**
During execution.

**CAUSE**
When programming zone limits “G20” or “G21” with parameters, the parameter value is greater than the maximum allowed for that function.

**SOLUTION**
Check the program history to make sure that this parameter does not have that value when it reaches the block where the limits have been defined.

**1090 ‘Point inside the forbidden zone 1.’**

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

**CAUSE**
An attempt has been made to move an axis to a point located inside the work area 1 that is defined as “no entry” zone.

**SOLUTION**
In the program history, work zone 1 (defined with G20/G21) has been set as “no entry” zone " (G22 K1 S1). To cancel this work zone, program “G22 K1 S0”

**1091 ‘Point inside the forbidden zone 2.’**

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

**CAUSE**
An attempt has been made to move an axis to a point located inside the work area 2 that is defined as “no entry” zone.

**SOLUTION**
In the program history, work zone 2 (defined with G20/G21) has been set as “no entry” zone “ (G22 K1 S1). To cancel this work zone, program “G22 K2 S0”
<table>
<thead>
<tr>
<th>Error code</th>
<th>Description</th>
<th>Detection</th>
<th>Cause</th>
<th>Solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>1092</td>
<td>'Insufficient acceleration for the speed programmed in threading.'</td>
<td>During execution.</td>
<td>A thread has been programmed and there isn't enough room to accelerate and decelerate.</td>
<td>Program a lower speed.</td>
</tr>
<tr>
<td>1093</td>
<td>'Only one Hirth axis can be moved at a time'</td>
<td></td>
<td></td>
<td>No explanation required.</td>
</tr>
<tr>
<td>1094</td>
<td>'Probe calibrated wrong'</td>
<td></td>
<td></td>
<td>No explanation required.</td>
</tr>
<tr>
<td>1095</td>
<td>'Probing axes out of alignment . '</td>
<td>During the probe calibration process.</td>
<td>An axis has moved to touch a cube and one of the axis that did not move registers a deflection greater than allowed by machine parameter MINDEFLE(P66). This is because the probing axes are not parallel enough to the axes of the machine.</td>
<td>Correct the parallelism between the probing axes and those of the machine.</td>
</tr>
<tr>
<td>1096</td>
<td>'Point inside the forbidden zone 3.'</td>
<td>During execution.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1097</td>
<td>'Point inside the forbidden zone 4.'</td>
<td>During execution.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1098</td>
<td>'Work zone limits defined wrong'</td>
<td>During execution.</td>
<td>The upper limits (G21) of the defined work zone are the same or smaller than the lower ones (G20) of the same work zone.</td>
<td>Program the upper limits (G21) of the work zone greater than the lower ones (G20).</td>
</tr>
<tr>
<td>1099</td>
<td>'Do not program a slaved axis.'</td>
<td>During execution.</td>
<td>When operating in polar coordinates, a movement has been programmed that involves an axis that is slaved to another one.</td>
<td>The movements in polar coordinates are made with the main axes of the work plane; therefore, the axes that define the plane cannot be slaved to each other or to a third one. To unslave the axes, program “G78”.</td>
</tr>
</tbody>
</table>
1100 ‘Travel limits of spindle 1 exceeded’

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. |
| CAUSE | An attempt has been made to exceed the physical turning limits of the spindle. As a result, the PLC activates the spindle mark “LIMIT+S” or “LIMIT-S”. (“LIMIT+S2” or “LIMIT-S2” when working with the second spindle). |

1101 ‘Spindle 1 locked’

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. |
| CAUSE | The CNC tries to output the command to the drive when the spindle input SERVOSON is still low. The error may be due to an error in the PLC program where this signal is not properly treated or that the value of the spindle parameter DWELL(P17) is not high enough. |

1102 ‘Following error of spindle 1 out of limit’

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output. |
| CAUSE | When the spindle is working in closed loop (M19), its following error is greater than the values indicated by spindle parameter MAXFLWE1(P21) and MAXFLE2(P22) The possible causes for this error are: Servo drive error  
Faulty drive. 
Enable signals missing. 
Power supply missing. 
Drive adjusted incorrectly. 
The velocity command signal is not received.  
Motor error  
Faulty motor. 
Power cables.  
Feedback failure  
Defective feedback.  
Defective feedback cable.  
Mechanical failure  
Mechanical stiffness.  
Spindle mechanically locked.  
CNC error  
Defective CNC.  
Parameters adjusted incorrectly. |

1103 ‘Do not synchronize spindles without homing them first’

| DETECTION | During execution. |
| CAUSE | An attempt has been made to synchronize the spindle without homing them first. |
| SOLUTION | Before activating the synchronization, both spindles must be homed using the “M19” function. |
1104 'Do not program G28 or G29 while spindle synchronization is active'

DETECTION During execution.
CAUSE An attempt has been made to swap spindles (G28/G29) while the spindles were synchronized.
SOLUTION First, cancel spindle synchronization (G78S).

1105 'Do not change gears while the spindles are synchronized'

DETECTION During execution.
CAUSE While the spindles are synchronized, a gear changing “M” function (M41 to M44) has been executed or the programmed “S” involves a gear change (with automatic gear changer).
SOLUTION First, cancel spindle synchronization (G78S).

1106 'Travel limits of spindle 2 exceeded'

Same as error 1100, but for the second spindle.

1107 'Spindle 2 locked'

Same as error 1101, but for the second spindle.

1108 'Following error of spindle 2 out of limit'

Same as error 1102, but for the second spindle.

1109 'Axis software limit overrun'

No explanation required.

1110-1118 'Range of the * axis exceeded'

DETECTION During execution.
CAUSE A movement has been defined with parameters and the parameter value is greater than the maximum travel distance of the axis.
SOLUTION Check the program history to make sure that this parameter does not have that value when it reaches the block where this movement is programmed.

1119-1127 'The * axis cannot be synchronized'

DETECTION During execution.
CAUSE The possible causes are:
1. When trying to synchronize two axes from the PLC and one axis is already slaved to another one using the “G77” function.
2. When programming or trying to move an axis that is slaved to another one.

1128-1136 'Maximum feedrate of the * axis exceeded'

DETECTION During execution.
CAUSE The resulting feedrate of one of the axes after applying an individual scaling factor exceeds the maximum value indicated by axis machine parameter MAXFEED (P42).

1137-1145 'Wrong feedrate parameter of the * axis'

DETECTION During execution.
CAUSE “G00” programmed with parameter G00FEED(P38)=0 or “G1 F00” with axis parameter MAXFEED(P42) = 0.

1146-1154 '* axis locked'

DETECTION During execution.
EFFECT It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel.
CAUSE The CNC tries to output the command to the drive when the spindle input SERVO(n)ON is still low. The error may be due to an error in the PLC program where this signal is not properly treated or that the value of the axis parameter Dwell(P17) is not high enough.
### 1155-1163 ‘Maximum axis limits of the * axis exceeded’

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. |
| CAUSE | A coordinate has been programmed that is out of the limits defined by axis parameters LIMIT+(P5) and LIMIT-(P6). |

### 1164-1172 ‘Work zone 1 of the * axis exceeded’

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. |
| CAUSE | An attempt has been made to move an axis to a point located out of the work area 1 that is defined as “no exit” zone. |
| SOLUTION | In the program history, work zone 1 (defined with G20/G21) has been set as “no exit” zone (G22 K1 S2). To cancel this work zone, program “G22 K1 S0” |

### 1173-1181 ‘Work zone 2 of the * axis exceeded’

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. |
| CAUSE | An attempt has been made to move an axis to a point located out of the work area 2 that is defined as “no exit” zone. |
| SOLUTION | In the program history, work zone 2 (defined with G20/G21) has been set as “no exit” zone (G22 K2 S2). To cancel this work zone, program “G22 K2 S0” |
### 1182-1190 'Following error of * axis out of limit'

**DETECTION**
During execution.

**EFFECT**
- It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.
- If it is in execution, it interrupts the execution of the part program of the CNC of its channel.
- Besides this, it activates the external emergency output.

**CAUSE**
The following error of the axis is greater than the values indicated by axis parameter MAXFLWE1(P21) or maxlwe2(P22). The possible causes for this error are:
- **Servo drive error**
  - Faulty drive.
  - Enable signals missing.
  - Power supply missing.
  - Drive adjusted incorrectly.
  - The velocity command signal is not received.
- **Motor error**
  - Faulty motor.
  - Power cables.
- **Feedback failure**
  - Defective feedback.
  - Defective feedback cable.
- **Mechanical failure**
  - Mechanical stiffness.
  - Spindle mechanically locked.
- **CNC error**
  - Defective CNC.
  - Parameters adjusted incorrectly.

### 1191-1199 'Difference of following errors of the slaved axis * tool large '

**EFFECT**
- It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.
- If it is in execution, it interrupts the execution of the part program of the CNC of its channel.
- Besides this, it activates the external emergency output.

**CAUSE**
The "n" axis is electronically coupled to another one or is a slaved Gantry axis and the difference between the following errors of the "n" axis and the one it is coupled to is greater than the value set by the machine parameter for the "n" axis MAXCOUPE(P45).

### 1200-1208 'Travel limits of the * axis exceeded'

**DETECTION**
During execution.

**EFFECT**
- It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.
- If it is in execution, it interrupts the execution of the part program of the CNC of its channel.
- Besides this, it activates the external emergency output.

**CAUSE**
An attempt has been made to exceed the physical travel limits. As a result, the PLC activates the axis mark "LIMIT+1" or "LIMIT-1".

### 1209-1217 '*' axis servo error'

**EFFECT**
- It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.
- If it is in execution, it interrupts the execution of the part program of the CNC of its channel.
- Besides this, it activates the external emergency output.

**CAUSE**
The real feedrate of the axis, after the time indicated by axis parameter FBALTIME(P12), is below 50% or over 200% of the one programmed.
1218-1226 ‘Work zone 3 of the * axis exceeded’

DETECTION During execution.

EFFECT It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

CAUSE An attempt has been made to move an axis to a point located out of the work area 3 that is defined as “no exit” zone.

SOLUTION In the program history, work zone 3 (defined with G20/G21) has been set as “no exit” zone ” (G22 K3 S2). To cancel this work zone, program “G22 K3 S0”

1228-1236 ‘Work zone 4 of the * axis exceeded’

DETECTION During execution.

EFFECT It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

CAUSE An attempt has been made to move an axis to a point located out of the work area 4 that is defined as “no exit” zone.

SOLUTION In the program history, work zone 4 (defined with G20/G21) has been set as “no exit” zone ” (G22 K4 S2). To cancel this work zone, program “G22 K4 S0”

1237 ‘Do not change the entry angle inside a thread’

DETECTION During execution.

CAUSE A thread joint has been defined and an entry angle "Q" has been programmed between two threads.

SOLUTION When joining threads, only the first one may have an entry angle “Q”.

1238 ‘Range of write-protected parameters. P297, P298’

DETECTION During execution.

CAUSE Parameters P297 and P298 are write-protected by means of machine parameters ROPARMIN(P51) and ROPARMAX(P52).

1239 ‘Point inside the forbidden zone 5.’

DETECTION During execution.

EFFECT It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

CAUSE An attempt has been made to move an axis to a point located inside the work area 5 that is defined as “no entry” zone.

SOLUTION In the program history, work zone 5 (defined with G20/G21) has been set as “no entry” zone ” (G22 K5 S1). To cancel this work zone, program “G22 K5 S0”

1240-1248 ‘Work zone 5 of the * axis exceeded’

DETECTION During execution.

EFFECT It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

CAUSE An attempt has been made to move an axis to a point located out of the work area 5 that is defined as “no exit” zone.

SOLUTION In the program history, work zone 5 (defined with G20/G21) has been set as “no exit” zone ” (G22 K5 S2). To cancel this work zone, program “G22 K5 S0”
### 1249 ‘Variable pitch thread programmed wrong’

**DETECTION**  
During execution.

**CAUSE**  
We are trying to make a variable-pitch thread with the following conditions:

- The “K” increment is positive and equal to or greater than 2L.
- The “K” increment is positive and with one of the calculated pitches, it exceeds the maximum feedrate (parameter MAXFEED) of one of the threading axis.
- The “K” increment is negative and one of the calculated pitches 0 or negative.

### 1250 ‘The K value is too large in G34’

**DETECTION**  
During execution.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

**CAUSE**  
The ratio between the initial and final pitches of the variable-pitch thread (G34) to be executed is greater than 32767.

### 1251 ‘Two variable-pitch threads cannot be joined in round corner’

**DETECTION**  
During motionless simulation, except when graphics are active.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

**CAUSE**  
To variable-pitch threads cannot be joined in round corner unless the second one is of the type: G34 ... L0 K0.

### 1252 ‘G5 G34 without a pitch is only allowed after a variable-pitch thread’

**DETECTION**  
During motionless simulation, except when graphics are active.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

**CAUSE**  
G34...L0 K0 (blending a variable pitch thread with another one with a fixed pitch) can only be programmed after a G34 with a K value other than ·0· and round corner (G05).

### 1253 ‘Retrace function unavailable’

**EFFECT**  
No explanation required.

It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

### 1254 ‘Parameter restricted to OEM programs’

**DETECTION**  
During execution.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

**CAUSE**  
An attempt has been made to use an OEM parameter P2000-P2255 in a program that has no OEM permission.

**SOLUTION**  
Use a non-OEM parameter.
1255 ‘Subroutine restricted to an OEM program’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.-</td>
</tr>
<tr>
<td></td>
<td>If it is in execution, it interrupts the execution of the part program of the CNC of its channel.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>An attempt has been made to use an OEM subroutine SUB10000-SUB20000 in a program that has no OEM permission.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Use a general subroutine P0000-P9999.</td>
</tr>
</tbody>
</table>
HARDWARE ERRORS

2000 'External emergency activated.'

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>PLC input I1 is set to “0” (maybe the E-stop button) or the PLC mark M5000(//EMERGEN) is set to “0”.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Check at the PLC why the inputs are at “0”. (Possible lack of power).</td>
</tr>
</tbody>
</table>

2001-2009 '* axis feedback error'

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>The CNC does not receive feedback signal from the axes.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Check that the connections are properly made. NOTE: This error comes up on differential axes DIFFBACK(P9) =YES and sinusoidal axes SINMAGNI(P10) other than 0 when parameter FBACKAL(P11)=ON Setting parameter FBACKAL(P11)=OFF avoids this error, but this is only temporary solution.</td>
</tr>
</tbody>
</table>

2010 ‘Spindle feedback error’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>The CNC does not receive feedback signal from the spindle.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Check that the connections are properly made. NOTE: This error comes up on differential axes DIFFBACK(P14)=YES when parameter FBACKAL(P15)=ON. Setting parameter FBACKAL(P15)=OFF avoids this error, but this is only temporary solution.</td>
</tr>
</tbody>
</table>

2011 ‘Maximum temperature exceeded’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>Any time.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>The CNC’s internal temperature has been exceeded. The causes may be: • Electrical cabinet poorly ventilated. • Axis board with some defective component.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Turn the CNC and wait until it cools off. If the error persists, a component of the board may be defective. In that case, replace the board. Contact the Service Department.</td>
</tr>
</tbody>
</table>
### 2012 'There is no voltage at the axis board'

**DETECTION**  
During execution.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  
24V are missing at the output supply of the axis board. The fuse may be blown.

**SOLUTION**  
Power the outputs of the axis board (24v). If the fuse is blown, replace it.

### 2013 'There is no voltage at the I/O 1 board.'

### 2014 'There is no voltage at the I/O 2 board.'

### 2015 'There is no voltage at the I/O 3 board.'

**DETECTION**  
During execution.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  
24V are missing at the output supply of the corresponding I/O board. The fuse may be blown.

**SOLUTION**  
Power the outputs of the corresponding I/O board (24v). If the fuse is blown, replace it.

### 2016 'The PLC is not ready.'

**DETECTION**  
During execution.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  
The PLC program is not running. These may be the probable causes:
- The PLC program is missing.
- WATCHDOG error.
- The program has been interrupted from monitoring.

**SOLUTION**  
Start the PLC program. (Restart the PLC).

### 2017 'CNC RAM memory error.'

**DETECTION**  
While starting the CNC or during diagnoses.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  
A defect has been found in the CNC's RAM memory.

**SOLUTION**  
Replace the CPU board. Contact the Service Department.

### 2018 'CNC's EPROM memory error.'

**DETECTION**  
While starting the CNC or during diagnoses.

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  
A defect has been found in the CNC's EPROM memory.

**SOLUTION**  
Replace the EPROM. Contact the Service Department.
**2019 ‘PLC’s RAM memory error.’**

| DETECTION | While starting the CNC or during diagnoses. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output. |
| CAUSE | A defect has been found in the PLC’s RAM memory. |
| SOLUTION | Replace the PLC board. Contact the Service Department. |

**2020 ‘PLC’s EPROM memory error.’**

| DETECTION | While starting the CNC or during diagnoses. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output. |
| CAUSE | A defect has been found in the PLC’s EPROM memory. |
| SOLUTION | Replace the EPROM. Contact the Service Department. |

**2021 ‘CNC’s user RAM memory error.’ Press any key.’**

| DETECTION | While starting the CNC or during diagnoses. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output. |
| CAUSE | A defect has been found in the CNC’s user RAM memory. |
| SOLUTION | Contact the Service Department. |

**2022 ‘CNC’s system RAM memory error.’ Press any key.’**

| DETECTION | While starting the CNC or during diagnoses. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output. |
| CAUSE | A defect has been found in the CNC’s system RAM memory. |
| SOLUTION | Contact the Service Department. |

**2023 ‘PLC’s RAM memory error.’ Press any key.’**

| DETECTION | While starting the CNC or during diagnoses. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output. |
| CAUSE | A defect has been found in the PLC’s RAM memory. |
| SOLUTION | Contact the Service Department. |
2026 ‘Probe’s maximum travel limit overrun.’

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output.

**CAUSE** The probe has exceeded the maximum deflection allowed by machine parameter.

**SOLUTION** Decrease the feedrate and check that the probe has not been damaged.

2027 ‘SERCOS chip RAM memory error.’ Press any key.’

**DETECTION** While starting the CNC or during diagnoses.

**CAUSE** A defect has been found in the SERCOS chip RAM memory.

**SOLUTION** Replace the SERCOS board. Contact the Service Department.

2028 ‘SERCOS chip version error.’ Press any key.’

**DETECTION** During CNC start-up.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output.

**CAUSE** The SERCOS chip version is old.

**SOLUTION** Replace the SERCOS chip. Contact the Service Department.

2029 ‘Feedback error at spindle 2.’

Same as error 2010, but for the second spindle.

2030 ‘Feedback over-current error.’

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output.

**CAUSE** There has been a short-circuit or the feedback device has overheated.

**SOLUTION** Check cables and connections.

2034 ‘There is no voltage at the I/O 4 board.’

2035 ‘There is no voltage at the I/O 5 board.’

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output.

**CAUSE** 24V are missing at the output supply of the corresponding I/O board. The fuse may be blown.

**SOLUTION** Power the outputs of the corresponding I/O board (24v). If the fuse is blown, replace it.
**2036 'The type of keyboard does not match the CNC model.'**

**DETECTION** During CNC start-up.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE** The keyboard identifier is unknown.

**SOLUTION** Contact the Service Department.

---

**2037 '24 V missing at the CPU-CNC module.'**

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE** 24 V missing at the CPU module of the CNC. The fuse may be blown.

**SOLUTION** Apply voltage to the CPU module of the CNC (24 V). If the fuse is blown, replace it.

---

**2041 'Unsupported LCD type.'**

**DETECTION** During CNC start-up.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE** The LCD identifier is unknown.

**SOLUTION** Contact the Service Department.

---

**2042 'It is recommended to lower the order of the frequency filter.'**

**DETECTION** On power-up or when pressing RESET after changing the value of the axis parameter or spindle parameter ORDER.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE** The order value of the FAGOR filter can cause overshooting.

**SOLUTION** Decrease the value of the order of the filter:

- A.m.p. ORDER (P70).
- S.m.p. ORDER (P67).

---

**2043 'Parameters of the frequency filter set wrong.'**

**DETECTION** On power-up or when pressing RESET after changing the value of some parameter of the filters.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE** The parameters for the frequency or order of the filter are set wrong. If it is executed with these wrong parameter values, the filter will not be active.

**SOLUTION** Check the values for the frequency and order of the filter.
2044 'TURBO board incompatible with version. Replace it with TURBO2.'

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. |
| CAUSE | If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output. |

2045 'G51 with FAGOR filters is incompatible with general parameter IPOTIME.'

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. |
| CAUSE | If it is in execution, it interrupts the execution of the part program of the CNC of its channel. Besides this, it activates the external emergency output. |

2046 'G51 with FAGOR filters is incompatible with parameter SMOTIME.'

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. |
| CAUSE | If any of the axes of the main channel has a.m.p. SMOTIME (P58) is other than ·0·, even if FAGOR filters are active with look ahead (bit 15 of g.m.p. LOOKATYP=1), when programming G51, the FAGOR filters will not start working. |

2047 'G51 with FAGOR filters is incompatible with parameter TYPE.'

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. |
| CAUSE | If any of the axes of the main channel has a.m.p. TYPE (P71) is other than ·2·, even if FAGOR filters are active with look ahead (bit 15 of g.m.p. LOOKATYP=1), when programming G51, the FAGOR filters will not start working. |

2048 'Parameter TYPE=2 is incompatible with general parameter IPOTIME.'

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. |
| CAUSE | If FAGOR filters are active (a.m.p. TYPE=2) and g.m.p. IPOTIME (P73) is other than ·0·, the FAGOR filters will not start working. |
2049 ‘Parameter TYPE=2 is incompatible with general parameter SMOTIME.’

**DETECTION**  During execution.

**EFFECT**  It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  If FAGOR filters are active (a.m.p. TYPE=2) and g.m.p. SMOTIME (P58) is other than ·0·, the FAGOR filters will not start working.

2051 ‘Too many feedback pulses.’

**DETECTION**  During execution.

**EFFECT**  It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  Axis feedrate too high due to gear ratio.

**SOLUTION**  Check axis gear ratio.

2052 ‘Too much real feedback difference.’

**DETECTION**  During execution.

**EFFECT**  It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  The possible causes are:

1. The difference between the position value of the linear encoder connected to the CNC (second feedback) and that of the motor encoder (first feedback) is greater than the value of a.m.p FBACKDIF (P100).

2. Feedback combination being active, the counting direction of the first and second feedback is not the same or the difference between the first and second feedback is greater than 838 mm.

**SOLUTION**  The solutions for each case are the following:

1. Check that the counting direction of both feedbacks is the same. Disable the feature that causes the error by setting a.m.p. FBACKDIF (P100) = 0.

2. Check that the counting direction of both feedbacks is the same.

2053 ‘Error at the CNC parameters.’

**DETECTION**  During execution.

**EFFECT**  It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of its channel.

Besides this, it activates the external emergency output.

**CAUSE**  A wrong value of some parameter has been detected on system start-up. The CNC indicates which parameter has the wrong value.

**SOLUTION**  Assign the right value to the parameter indicated by the CNC.
Error solution

· T · Model

Ref. 1010
PLC ERRORS

3000 ' (PLC_ERR without description)'

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.</td>
</tr>
<tr>
<td></td>
<td>If it is in execution, it interrupts the execution of the part program of the CNC of all channels.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>Marks ERR1 to ERR64 have been set to “1”.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Check at the PLC why these marks are set to “1” and act accordingly.</td>
</tr>
</tbody>
</table>

3001 'WATCHDOG in the main module (PRG).'

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>Any time.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.</td>
</tr>
<tr>
<td></td>
<td>If it is in execution, it interrupts the execution of the part program of the CNC of all channels.</td>
</tr>
<tr>
<td></td>
<td>Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>The possible causes are:</td>
</tr>
<tr>
<td></td>
<td>1. The execution of the PLC's main program has exceeded the time set in PLC parameter WAGPRG(P0).</td>
</tr>
<tr>
<td></td>
<td>2. The program is in an endless loop.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Increase the time of PLC parameter WAGPRG(P0) or increase the PLC speed.</td>
</tr>
<tr>
<td></td>
<td>• Insert CPU TURBO.</td>
</tr>
<tr>
<td></td>
<td>• Change PLC parameter CPUTIME(P26) or general parameter LOOPTIME(P72).</td>
</tr>
</tbody>
</table>

3002 'WATCHDOG in the periodic module (PE).'

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>Any time.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.</td>
</tr>
<tr>
<td></td>
<td>If it is in execution, it interrupts the execution of the part program of the CNC of all channels.</td>
</tr>
<tr>
<td></td>
<td>Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>The possible causes are:</td>
</tr>
<tr>
<td></td>
<td>1. The execution of the PLC's periodic program has exceeded the time set in PLC parameter WAGPER(P1).</td>
</tr>
<tr>
<td></td>
<td>2. The program is in an endless loop.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Increase the time of PLC parameter WAGPER(P1) or increase the PLC speed.</td>
</tr>
<tr>
<td></td>
<td>• Insert CPU TURBO.</td>
</tr>
<tr>
<td></td>
<td>• Change PLC parameter CPUTIME(P26) or general parameter LOOPTIME(P72).</td>
</tr>
</tbody>
</table>

3003 'Division by zero at the PLC'

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>Any time.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.</td>
</tr>
<tr>
<td></td>
<td>If it is in execution, it interrupts the execution of the part program of the CNC of all channels.</td>
</tr>
<tr>
<td></td>
<td>Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>In the PLC program, there is a line whose execution implies a division by zero.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>When working with registers, that register may have already acquired a zero value. Check that the register does not reach the operation with that value.</td>
</tr>
</tbody>
</table>
3004 'PLC error -> '

DETECTION Any time.
EFFECT It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.
CAUSE An error has been detected on the PLC board.
SOLUTION Replace the PLC board. Contact the Service Department.

3005 'Contacts debugging error'

DETECTION While debugging the PLC program.
CAUSE When debugging the PLC program to create the PLC program in contacts (ladder), the CNC finds an error in that program.
SOLUTION Check if it has been properly compiled.

3006 'The PLC program does not exist'

No explanation required.

3007 'Configuration file corrupted'

DETECTION At any time, while being on the <CONTACTS> screen.
CAUSE An error has occurred in the configuration file.
SOLUTION Exit the <CONTACTS> screen and go back into it.

3008 'PLC program too large'

DETECTION At any time, while being on the <CONTACTS> screen.
CAUSE The PLC program has exceeded the maximum size limit.
### SERVO ERRORS

**4000 ‘Sercos ring error’**

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1-.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
SERCOS communication has been interrupted. It may be caused by an interruption in the connection ring (optical fiber disconnected or broken) or by a wrong configuration.

1. The identifying wheel does not match the sercosid.
2. Parameter P120 (SERSPD) does not match the transmission speed.
3. The drive version is incompatible with the CNC.
4. There is an error on the SERCOS board.
5. Different transmission speed (baudrate) at the drive and at the CNC.

A drive has been turned off and back on due to a power supply failure. When starting up again, it displays the error **4027 ‘The drive has started up again’**

An attempt has been made to read or write an non-existent variable or too many variables in a drive through the fast channel.

**SOLUTION**
To check that the connection ring is not interrupted, check that the light goes through the optical fiber. If it is due to a wrong configuration, contact the Service Department.

If the error is due to the fast channel:

- Check that all the variables to be read or written through the fast channel actually exist.
- Save the SERCOS LOG into a file and see which axis causes the error.
- Set PLC machine parameters “SRD700 and SWR800” of that drive to “0”.
- Reset the CNC and verify that no errors come up.
- Set the parameters one by one to the desired value until the failure occurs.
- When locating the parameter, look that variable up in the drive manual to verify that it exists in that version and it may be accessed. If so, the error may come up because it tries read or write too many variables in that drive.

**4001 ‘Undefined class 1 error’**

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1-.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
The drive has detected an error, but it cannot identify it.

**SOLUTION**
Contact the Service Department.
<table>
<thead>
<tr>
<th>Error Number</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4002</td>
<td>‘Overload (201...203)’</td>
</tr>
<tr>
<td>4003</td>
<td>‘Overtemperature at the drive (107)’</td>
</tr>
<tr>
<td>4004</td>
<td>‘Overtemperature at the motor (108)’</td>
</tr>
<tr>
<td>4005</td>
<td>‘Overtemperature at the heatsink (106)’</td>
</tr>
<tr>
<td>4006</td>
<td>‘Voltage control error (100...105)’</td>
</tr>
<tr>
<td>4007</td>
<td>‘Feedback error (600...606)’</td>
</tr>
<tr>
<td>4008</td>
<td>‘Error at the power bus (213...215)’</td>
</tr>
<tr>
<td>4009</td>
<td>‘Overcurrent (212)’</td>
</tr>
<tr>
<td>4010</td>
<td>‘Overvoltage at the power bus (304/306)’</td>
</tr>
<tr>
<td>4011</td>
<td>‘Undervoltage at the power bus (307)’</td>
</tr>
</tbody>
</table>

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.

**CAUSE** An error occurred at the drive. The number in brackets indicates the standard error number of the drive. Refer to the drive manual for further information.

**SOLUTION** These types of error come with the messages 4019, 4021, 4022 or 4023 that indicate in which axis or spindle drive the error came up. Refer to the drive manual to check the error (number in brackets) and act accordingly.

<table>
<thead>
<tr>
<th>Error Number</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4012</td>
<td>‘Drive error’</td>
</tr>
<tr>
<td>4013</td>
<td>‘Position deviation too high’</td>
</tr>
<tr>
<td>4014</td>
<td>‘Communications error’</td>
</tr>
<tr>
<td>4015</td>
<td>‘Travel limit overrun’</td>
</tr>
</tbody>
</table>

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.

**CAUSE** An error occurred at the drive.

**SOLUTION** Refer to the drive manual.

<table>
<thead>
<tr>
<th>Error Number</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4016</td>
<td>‘Undefined class 1 error’</td>
</tr>
</tbody>
</table>

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.

**CAUSE** The drive has detected an error, but it cannot identify it.

**SOLUTION** Contact the Service Department.

<table>
<thead>
<tr>
<th>Error Number</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4017</td>
<td>‘Drive error’</td>
</tr>
</tbody>
</table>

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.

**CAUSE** An error occurred at the drive.

**SOLUTION** Refer to the drive manual.
4018 ‘Error accessing a variable’

**DETECTION**
During execution.

**CAUSE**
An attempt has been made to read (or write) a SERCOS variable from the CNC and:
1. That variable does not exist.
2. The maximum/minimum values have been exceeded.
3. The SERCOS variable has a variable length.
4. An attempt has been made to write a read-only variable.

**SOLUTION**
Check that the variable to be associated with an action is of the right type.

4019 ‘Drive error: Axis’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.
Besides this, it activates the external emergency output.

**CAUSE**
These messages come with errors 4002 – 4011. When one of the mentioned errors occurs, they indicate in which axis it came up.

4020 ‘DRIBUSID parameter value error’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.
Besides this, it activates the external emergency output.

**CAUSE**
An error occurred at the drive.

**SOLUTION**
Refer to the drive manual.

4021 ‘Spindle drive error :’

4022 ‘Spindle-2 drive error :’

4023 ‘Auxiliary spindle drive error’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.
Besides this, it activates the external emergency output.

**CAUSE**
These messages come with errors 4002 – 4011. When one of the mentioned errors occurs, they indicate in which spindle it came up.

4024 ‘Error when searching home.’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.
Besides this, it activates the external emergency output.

**CAUSE**
The home search command of SERCOS has been executed incorrectly.
### 4025 ‘Loop time exceeded: Increase P72 (looptime)’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
The time it takes to calculate the feedrate of the axis is greater than the cycle time established for transmission to the drive.

**SOLUTION**
Increase the value of general machine parameter LOOPTIME (P72). If the error persists, contact the Service Department.

### 4026 ‘SERCOS chip RAM memory error’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**SOLUTION**
Contact the service department to replace the SERCOS board.

### 4027 ‘The drive has started up again’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
A drive has been turned off and back on due to a power supply failure.

### 4028 ‘The light does not reach the CNC through the optic fiber’

**DETECTION**
On power-up.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
The signal sent by the CNC through the optical fiber does not return to the CNC.

**SOLUTION**
Check the condition and installation of the fiber optic cables. Check that the light going “OUT” of the CNC is going through the drives and comes “IN”to the CNC.

If the cables are OK, remove the drives from the ring until the error no longer comes up.
### 4029 ‘Communication with the drive cannot be established. No response’

| DETECTION | On power-up. The drive stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. |
| CAUSE | A drive is not responding to the signal sent by the CNC due to one of these causes:  
- The drive does not recognize the sercos board.  
- The drive is locked up.  
- The switch number has not been properly read.  
- The SERCOS transmission speed has been set differently at the drives and at the CNC. General parameter SERSPD at the CNC and QP11 at the drives. |
| SOLUTION | Save the SERCOS LOG into a file. See the value of axis machine parameter SERCOSID of the axis causing the error. Check that the ring contains a drive with the switch in that position. Reset the drive because the drive only reads the switch on power-up. Check that the CNC and the drives have the same transmission speed. General parameter SERSPD at the CNC and QP11 at the drives. Check that the drive does not issue sercos board. To do that look at the display of the drive. If it shows hardware errors, change the drive's sercos board. If there are no errors at that drive, set the switch of the drive to “1”, reset it, set the CNC with a single Sercos axis and connect to the CNC. If it still issues the error, change the drive. |

### 4030 ‘SERCON register writing error’

| DETECTION | During execution. The drive stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. |
| SOLUTION | Contact the Service Department. |

### 4032 ‘Handshake error’

| DETECTION | During the operation of the CAN bus. The handshake bit has been lost. To verify that the communication is correct, it continuously checks a handshake bit between the CNC and the drives. |
| CAUSE | The handshake bit has been lost. To verify that the communication is correct, it continuously checks a handshake bit between the CNC and the drives. |
| SOLUTION | Check the cables, the connections, the line terminating resistors and the CAN boards (at the CNC and at the drive). |

### 4033 ‘Cyclic message of the drive lost’

| DETECTION | During the operation of the CAN bus. The message of the drive has been lost (it has not reached the CNC). |
| CAUSE | A message of the drive has been lost (it has not reached the CNC). |
| SOLUTION | Check the cables, the connections, the line terminating resistors and the CAN boards (at the CNC and at the drive). |
### 4034 'SID reading error’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During the operation of the CAN bus.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>From a CNC channel, an attempt has been made to read a non-existent variable of the drive.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Check that the variable that it is trying to read exists at the drive.</td>
</tr>
</tbody>
</table>

### 4035 'SERCOS communication saturated. Increase P178 (SERCD1)’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>On SERCOS bus power-up.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>The maximum bus capacity has been exceeded.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Increase the Sercos transmission delay using g.m.p. SERCDEL1 (P178).</td>
</tr>
</tbody>
</table>

### 4036 'SERCOS T3 > T4. Decrease P179 (SERCD2)’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>On SERCOS bus power-up.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>The value of g.m.p. SERCDEL2 (P179) is wrong.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Contact the Service Department.</td>
</tr>
</tbody>
</table>

### 4050 ‘ERROR 1: Internal (fatal error): Internal RAM check failed’

### 4051 ‘ERROR 2: Internal (fatal error): Internal program malfunctioning problem’

### 4052 ‘ERROR 3: Power bus drop: There is no torque’

### 4053 ‘ERROR 4: The emergency stop cannot stop the motor in the established time frame’

### 4054 ‘ERROR 5: Program code checksum error’

### 4055 ‘ERROR 6: Sercos board error’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During execution.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFFECT</td>
<td>It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output.</td>
</tr>
<tr>
<td>CAUSE</td>
<td>An error occurred at the drive.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Refer to the drive manual.</td>
</tr>
</tbody>
</table>
4056 ‘ERROR 100: Internal +5 V out of range’
4057 ‘ERROR 101: Internal -5 V out of range’
4058 ‘ERROR 102: Internal +8 V out of range’
4059 ‘ERROR 103: Internal -8 V out of range’
4060 ‘ERROR 104: Internal +18 V out of range’
4061 ‘ERROR 105: Internal -18 V out of range’
4062 ‘ERROR 106: Heatsink overheated’
4063 ‘ERROR 107: VeCon card overheated’
4064 ‘ERROR 108: Motor overheated’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
An error occurred at the drive.

**SOLUTION**
Refer to the drive manual.

4065 ‘ERROR 200: Over-speed’
4066 ‘ERROR 201: Motor overload’
4067 ‘ERROR 202: Drive overload’
4068 ‘ERROR 211: Internal (fatal error): DSP program execution error’
4069 ‘ERROR 212: Over-current’
4070 ‘ERROR 213: Undervoltage at the IGBT power driver’
4071 ‘ERROR 214: Short-circuit’

4072 ‘ERROR 215: Over-voltage at the power bus (Hard)’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
An error occurred at the drive.

**SOLUTION**
Refer to the drive manual.

4073 ‘ERROR 300: Heatsink of the power supply module overheated’
4074 ‘ERROR 301: Ballast circuit of the power supply module heatsink overheated’
4075 ‘ERROR 302: Short-circuit at the ballast circuit of the power supply module’
4076 ‘ERROR 303: Ballast circuit supply voltage out of range’
4077 ‘ERROR 304: Over-voltage at the power bus detected by the power supply module’
4078 ‘ERROR 305: Protocol error on the interface between the power supply module and the driver’
4079 ‘ERROR 306: Over-voltage at the power bus (Soft, trigger prior to hardware )’
4080 ‘ERROR 307: Under-voltage of the power bus’

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
An error occurred at the drive.

**SOLUTION**
Refer to the drive manual.
4081 'ERROR 400: No SERCOS board detected'
4082 'ERROR 401: Internal SERCOS error'
4083 'ERROR 403: MST fault'
4084 'ERROR 404: MDT fault'
4085 'ERROR 405: Wrong phase (> 4)'
4086 'ERROR 406: Wrong phase up'
4087 'ERROR 407: Wrong phase down'
4088 'ERROR 408: Phase change without "ready" acknowledgement'
4089 'ERROR 409: Change to an uninitialized phase'
4090 'ERROR 410: Noise resets sercon'

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. |
| CAUSE | An error occurred at the drive. |
| SOLUTION | Refer to the drive manual. |

4091 'ERROR 500: Incoherent parameters’
4092 'ERROR 501: Parameter checksum error’
4093 'ERROR 502: Wrong parameter value’
4094 'ERROR 503: The table for default parameter values for each motor is wrong’
4095 'ERROR 504: Wrong parameter in SERCOS phase 2’
4096 'ERROR 505: Different RAM and Flash parameters’

| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. |
| CAUSE | An error occurred at the drive. |
| SOLUTION | Refer to the drive manual. |

4097 'ERROR 600: Communication error with the second feedback’
4098 'ERROR 601: Communication error with the rotor encoder’
4099 'ERROR 602: Motor feedback B signal saturation’
4100 'ERROR 603: Motor feedback A signal saturation’
4101 'ERROR 604: Saturation of A and/or B signal values’
4102 'ERROR 605: A and/or B signal values too low’
4103 'ERROR 606: Too much dispersion of the rotor sensor signals’

<p>| DETECTION | During execution. |
| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. |
| CAUSE | An error occurred at the drive. |
| SOLUTION | Refer to the drive manual. |</p>
<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4104 'ERROR 700: RS232 board error'</td>
<td></td>
</tr>
<tr>
<td>4105 'ERROR 701: Internal: Wrong VeCon board identification'</td>
<td></td>
</tr>
<tr>
<td>4106 'ERROR 702: Expansion board identification error'</td>
<td></td>
</tr>
<tr>
<td>4107 'ERROR 703: I/O board identification error'</td>
<td></td>
</tr>
<tr>
<td>4108 'ERROR 704: Analog board identification error'</td>
<td></td>
</tr>
<tr>
<td>4109 'ERROR 705: Power board identification error'</td>
<td></td>
</tr>
<tr>
<td>4110 'ERROR 706: X3 encoder simulation board identification error'</td>
<td></td>
</tr>
<tr>
<td>4111 'ERROR 707: X4 motor feedback board identification error'</td>
<td></td>
</tr>
</tbody>
</table>

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE** An error occurred at the drive.

**SOLUTION** Refer to the drive manual.

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4112 'ERROR 801: Encoder not found'</td>
<td></td>
</tr>
<tr>
<td>4113 'ERROR 802: Error when communicating with the encoder'</td>
<td></td>
</tr>
<tr>
<td>4114 'ERROR 803: Encoder not initialized'</td>
<td></td>
</tr>
<tr>
<td>4115 'ERROR 804: Defective encoder'</td>
<td></td>
</tr>
<tr>
<td>4116 'ERROR 805: No encoder has been detected on the motor'</td>
<td></td>
</tr>
</tbody>
</table>

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE** An error occurred at the drive.

**SOLUTION** Refer to the drive manual.

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4117 'ERROR 7: SERCON clock error'</td>
<td></td>
</tr>
<tr>
<td>4118 'ERROR 8: SERCON data error'</td>
<td></td>
</tr>
<tr>
<td>4119 'ERROR 203: Torque overload error'</td>
<td></td>
</tr>
<tr>
<td>4120 'ERROR 411: telegram reception error'</td>
<td></td>
</tr>
<tr>
<td>4121 'ERROR 109: Over-voltage at the digital input'</td>
<td></td>
</tr>
<tr>
<td>4122 'ERROR 110: Low heat-sink temperature'</td>
<td></td>
</tr>
<tr>
<td>4123 'ERROR 607: Direct feedback A and/B signal saturation'</td>
<td></td>
</tr>
<tr>
<td>4124 'ERROR 608: Too much damping of A and/B feedback signals of the direct feedback'</td>
<td></td>
</tr>
<tr>
<td>4125 'ERROR 609: Temperature sensor error'</td>
<td></td>
</tr>
<tr>
<td>4126 'ERROR 150: 'Travel limits exceeded'</td>
<td></td>
</tr>
<tr>
<td>4127 'ERROR 152: Command module exceeded'</td>
<td></td>
</tr>
<tr>
<td>4128 'ERROR 153: Excessive deviation of the position command'</td>
<td></td>
</tr>
</tbody>
</table>

**DETECTION** During execution.

**EFFECT** It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE** An error occurred at the drive.

**SOLUTION** Refer to the drive manual.
<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ERROR 154</td>
<td>Excessive feed-forward velocity command</td>
</tr>
<tr>
<td>ERROR 155</td>
<td>Excessive feed-forward acceleration command</td>
</tr>
<tr>
<td>ERROR 156</td>
<td>Excessive following error</td>
</tr>
<tr>
<td>ERROR 157</td>
<td>Too much difference between the positions of the two feedbacks</td>
</tr>
<tr>
<td>ERROR 250</td>
<td>Home search error</td>
</tr>
<tr>
<td>ERROR 251</td>
<td>DriveControlledHoming command error</td>
</tr>
<tr>
<td>ERROR 253</td>
<td>Home not found in 2 revolutions</td>
</tr>
<tr>
<td>ERROR 254</td>
<td>Wrong reading of distance-coded reference marks</td>
</tr>
<tr>
<td>ERROR 308</td>
<td>Over-current in the regeneration circuit</td>
</tr>
<tr>
<td>ERROR 309</td>
<td>Short-circuit at the High Side IGBT</td>
</tr>
<tr>
<td>ERROR 310</td>
<td>Under-voltage at the driver of the High Side IGBT</td>
</tr>
<tr>
<td>ERROR 311</td>
<td>Short-circuit at the Low Side IGBT</td>
</tr>
<tr>
<td>ERROR 312</td>
<td>Under-voltage at the driver of the Low Side IGBT</td>
</tr>
</tbody>
</table>

**DETECTION**
During execution.

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to 1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
An error occurred at the drive.

**SOLUTION**
Refer to the drive manual.
Error solution

4154 ‘ERROR 808 : No encoder has been detected in Feedback2’
4155 ‘ERROR 809 : Communication error with the Feedback2 encoder’
4156 ‘ERROR 810 : Uninitialized Feedback2 encoder’
4157 ‘ERROR 811 : Defective Feedback2 encoder’
4158 ‘ERROR 255: Error when switching feedbacks after executing the command PC150’
4159 ‘ERROR 812 : Feedback2 encoder detected’
4160 ‘ERROR 206: Excessive velocity command’

DETECTION During execution.
EFFECT It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.
Besides this, it activates the external emergency output.
CAUSE An error occurred at the drive.
SOLUTION Refer to the drive manual.

4177 ‘ERROR 205: The motor has not enough voltage for the required torque’
4178 ‘ERROR 315: The power supply has not started-up properly’
4179 ‘ERROR 610 : Wrong absolute signals’
4180 ‘ERROR 611: The axis moves on power-up and the position cannot be read’

DETECTION During execution.
EFFECT It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.
Besides this, it activates the external emergency output.
CAUSE An error occurred at the drive.
SOLUTION Refer to the drive manual.
Error solution

· T · Model

Ref. 1010
5003 ‘Application error’

**EFFECT**

It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**

Internal CANopen error.

**SOLUTION**

Contact the Service Department.

5004 ‘CAN bus error’

**EFFECT**

It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**

The error type is indicated with a code:

2 Transmission queue full, the message cannot be sent.
128 Bus Off, the bus has been deactivated due to too many errors.
129 CAN warning, there are more than 96 errors at the bus, step prior to the bus off error.
130 Loss of message received or too many messages received. Usually due to wrong speed for the cable length.
131 The CNC has switched to an inoperative state in the bus (internal).

**SOLUTION**

The solution for each cause is:

2 Check the connection between the CNC and first node.
128 Check cables and connections.
129 Check cables and connections.
130 Check machine parameter IOCANSPE (P88).
131 Check cables and connections.

5005 ‘Presence control error detected by the CNC’

**EFFECT**

It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**

The CNC detects that the node has reset itself or is connected wrong.

**SOLUTION**

Check cables and connections.

5006 ‘Error because the node has been reset’

**EFFECT**

It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to ·1·.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**

The node has been reset due to a power supply failure.

**SOLUTION**

Check the power supply voltage at the indicated node, the ground connection and the load of the outputs.
5007 ‘Corrected error’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
It is activated when an error situation disappears and shows whether there are any more left. If there is none, it resets the node connections.

**SOLUTION**
Access the Status screen > Can > Versions and reload the software.

5022 ‘Internal software’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
Internal node software error.

**SOLUTION**
Access the Status screen > Can > Versions and reload the software.

5027 ‘Communication’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
Node communication error.

**SOLUTION**
Contact the Service Department.

5028 ‘Lost messages’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
The node has lost messages.

**SOLUTION**
Check cables and connections.

5029 ‘Presence control error detected by the node’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
The presence control done by the CNC node has failed.

**SOLUTION**
Check cables and connections.

5030 ‘Protocol error’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1. If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
The node has received a message that it cannot interpret.

**SOLUTION**
Contact the Service Department.
### 5031 ‘PDO not processed due to its length’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
The node has received a process message whose length does not match.

**SOLUTION**
Contact the Service Department.

### 5032 ‘PDO too long’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
The node has received a process message longer than the one programmed.

**SOLUTION**
Contact the Service Department.

### 5036 ‘Output over-current’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
Excessive consumption (over current) has been detected in the outputs of the indicated node. As a precaution, the system deactivates all the outputs of this module setting them to zero volts.

**SOLUTION**
Check the consumption and possible short-circuits at the outputs of the module.

### 5037 ‘Power supply voltage error’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
A power supply failure has been detected at the indicated node, it has no power or it is under +24V.

**SOLUTION**
Check the supply voltage at the outputs and the consumption of the module’s supply voltage.

### 5039 ‘No response (identifier).’

**EFFECT**
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.

If it is in execution, it interrupts the execution of the part program of the CNC of all channels.

Besides this, it activates the external emergency output.

**CAUSE**
Error in the node configuration.

**SOLUTION**
Check cables and connections.
### 5041 ‘It has no digital inputs’

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.  
If it is in execution, it interrupts the execution of the program of the CNC of all channels.  
Besides this, it activates the external emergency output.

**CAUSE**  
Error in the node configuration.

**SOLUTION**  
Check cables and connections.

### 5045 ‘Writing the transmission mode TPDO1.’

### 5046 ‘Writing the reception mode RPDO1.’

### 5047 ‘Writing the reception mode RPDO2.’

### 5048 ‘Writing - Life Time Factor’

### 5049 ‘Writing - Guard Time’

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.  
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.  
Besides this, it activates the external emergency output.

**CAUSE**  
Error in the node configuration.

**SOLUTION**  
Check cables and connections.

### 5051 ‘PT100 broken or not connected’

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.  
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.  
Besides this, it activates the external emergency output.

**SOLUTION**  
Check that the PT100 is connected and not broken.

### 5052 ‘Too many errors at the bus’

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.  
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.  
Besides this, it activates the external emergency output.

**CAUSE**  
Error in the node configuration.

**SOLUTION**  
Check cables and connections.

### 5055 ‘Writing the reception mode RPDO3’

### 5058 ‘Writing the reception mode RPDO4’

### 5061 ‘Writing the transmission mode TPDO2.’

**EFFECT**  
It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to -1.  
If it is in execution, it interrupts the execution of the part program of the CNC of all channels.  
Besides this, it activates the external emergency output.

**CAUSE**  
Error in the node configuration.

**SOLUTION**  
Check cables and connections.
5062 'It could not disable the PT100 1'

5063 'It could not disable the PT100 2'

| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to \(-1\). If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. 

| CAUSE | Error in the node configuration. |

5064 'It could not enable the analog inputs'

| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to \(-1\). If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. 

| CAUSE | Error in the node configuration. |

5065 'No communication with CAN drives'

| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to \(-1\). If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. 

| CAUSE | CAN communication has been interrupted. 
SOLUTION | Check cables and connections. |

5066 'Error reading parameter SRR700, SWR800 SID'

| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to \(-1\). If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. 

| CAUSE | Using PLC parameters 700/800, a CAN variable has been requested that does not exist at the drive. 
SOLUTION | Check that the variables that it is trying to read exist at the drive. |

5067 'Too many PLC parameters SRR700.'

| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to \(-1\). If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. 

| CAUSE | Too many parameters are requested from the drive. 
SOLUTION | Set some PLC parameters SRR700 (P28-P67) to 0 to request fewer variables from the drive. |

5068 'Too many PLC parameters SWR800.'

| EFFECT | It stops the movement of the axes and the spindle, eliminating all the enable signals and canceling all the analog outputs of the CNC. When detected from the position loop, it opens the position loop and sets the LOPEN mark to \(-1\). If it is in execution, it interrupts the execution of the part program of the CNC of all channels. Besides this, it activates the external emergency output. 

| CAUSE | Too many parameters are requested from the drive. 
SOLUTION | Set some PLC parameters SWR800 (P68-P87) to 0 to request fewer variables from the drive. |
TABLE DATA ERRORS

‘CHECKSUM ERROR GENERAL PARAMETERS Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR SPINDLE PARAMETERS Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR 2nd SPINDLE PARAM. Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR AUX. SPINDLE PARAM. Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR SERIAL LINE 1 PARAM. Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR SERIAL LINE 2 PARAM. Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR HD/ETHERNET PARAM. Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR USER PARAMETERS Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR OEM PARAM. Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR PLC PARAMETERS Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR ZERO OFFSET TABLE Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR PASSWORD TABLE Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR AXIS * PARAMETERS Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR: TOOL TABLE Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR TOOL OFFSET TABLE Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR MAGAZINE TABLE Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR M FUNCTION TABLE Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR LEADScrew * TABLE Load CARD A? (ENTER/ESC)’
‘CHECKSUM ERROR CROSS COMP. TABLE * Load CARD A? (ENTER/ESC)’
‘ERROR: GEOMETRY TABLE CHECKSUM Load CARD A? (ENTER/ESC)’

DETECTION During CNC start-up.
CAUSE Certain table data has been lost (possible RAM error) and there is a table saved in CARD A.
SOLUTION Pressing [ENTER] copies the table saved in CARD A to RAM memory. If the error persists, contact the service department.
DETECTION During CNC start-up.

CAUSE Certain table data has been lost (possible RAM error) and there is no table saved in CARD A.

SOLUTION Pressing [ENTER] loads the tables with CNC's default values. If the error persists, contact the Service Department.
### ‘Wrong * leadscrew table. Press key’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During CNC start-up.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>There is some erroneous data in the parameters of the leadscrew compensation table.</td>
</tr>
</tbody>
</table>
| SOLUTION   | The definition of the points of the table must meet the following requirements:  
  - The points of the table must be ordered according to their position on the axis, starting from the most negative or less positive point to be compensated.  
  - The machine reference point must have no error (zero).  
  - The error difference between consecutive points cannot be greater than the distance between them. |

### ‘Wrong * cross compensation table. Press key’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During CNC start-up.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>There is some erroneous data in the parameters of the cross compensation table.</td>
</tr>
</tbody>
</table>
| SOLUTION   | The definition of the points of the table must meet the following requirements:  
  - The points of the table must be ordered according to their position on the axis, starting from the most negative or less positive point to be compensated.  
  - The machine reference point must have no error (zero). |

### ‘Incorrect cross compensation table parameters’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During CNC start-up.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>The parameters indicating the axes involved in the cross compensation are defined wrong.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Maybe a nonexistent axis has been defined or the affected axis (to be compensated) and the one affecting it are the same.</td>
</tr>
</tbody>
</table>

### ‘Wrong axis or spindle parameters sercosid’

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>During CNC start-up.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>The servosid parameters have not been entered correctly.</td>
</tr>
</tbody>
</table>
| SOLUTION   | The rules of sercosid parameters are:  
  - They must begin with number 1.  
  - They must be consecutive.  
  - They cannot be repeated. |
ERRORS OF THE TC WORK MODE

9001 ‘Cycle without ROUGHING or FINISHING’

DETECTION While executing a drilling, facing, taper turning, rounding or profile cycle.
CAUSE Neither the roughing nor the finishing tools have been selected.
SOLUTION Select the roughing tool (if T=0, there is no roughing) and the finishing tool (if T=0, there is no finishing).

9002 ‘ROUGHING: Value of $\Delta=0$’

DETECTION While executing a drilling, facing, taper turning, rounding or profile cycle.
CAUSE The tapping depth “$\Delta$” has not been defined.
SOLUTION Program a cutting pass greater than zero.

9003 ‘ROUGHING: Value of $F=0$’

DETECTION While executing a drilling, facing, taper turning, rounding or profile cycle.
CAUSE No roughing feedrate “F” has been selected.
SOLUTION Program a positive feedrate “F” other than zero.

9004 ‘ROUGHING: Value of $S=0$’

DETECTION While executing a drilling, facing, taper turning, rounding or profile cycle.
CAUSE No roughing spindle speed “S” has been selected.
SOLUTION Program a positive spindle speed “S” other than zero.

9005 ‘FINISHING: Value of $F=0$’

DETECTION While executing a drilling, facing, taper turning, rounding or profile cycle.
CAUSE No finishing feedrate “F” has been selected.
SOLUTION Program a positive feedrate “F” other than zero.

9006 ‘FINISHING: Value of $S=0$’

DETECTION While executing a drilling, facing, taper turning, rounding or profile cycle.
CAUSE No finishing spindle speed “S” has been selected.
SOLUTION Program a positive spindle speed “S” other than zero.

9007 ‘GEOMETRY: Value of $Z_i=Z_f$’

DETECTION While executing a turning, facing, taper turning or grooving cycle.
CAUSE The Z coordinate of the starting and end points are the same.
SOLUTION The Z coordinate of the starting and end points must be different.

9008 ‘GEOMETRY: Value of $X=\Phi$’

DETECTION While executing a turning, facing, taper turning or grooving cycle.
CAUSE The X coordinate of the starting and end points is the same.
SOLUTION The X coordinate of the starting and end points must be different from that of the final diameter.

9009 ‘FINISHING: Impossible finishing stock’

DETECTION While executing a turning, facing or grooving cycle.
CAUSE The finishing stock is greater than the total machining depth.
SOLUTION The finishing stock must be smaller than the total machining depth.

9010 ‘GEOMETRY: Wrong angle value’

DETECTION While executing a taper turning cycle.
CAUSE The taper angle is smaller than 0º or greater than 90º.
SOLUTION The taper angle must be between 0º and 90º.
<table>
<thead>
<tr>
<th>Error Code</th>
<th>Error Description</th>
<th>Detection</th>
<th>Cause</th>
<th>Solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>9011</td>
<td>'GEOMETRY: Wrong radius value'</td>
<td>While executing a rounding cycle.</td>
<td>No rounding radius has been defined.</td>
<td>Program a rounding radius other than zero.</td>
</tr>
<tr>
<td>9012</td>
<td>'THREADING: Value of T=0'</td>
<td>While executing a threading cycle.</td>
<td>The tool number has not been defined.</td>
<td>The tool number must be other than zero.</td>
</tr>
<tr>
<td>9013</td>
<td>'THREADING: Value of S=0'</td>
<td>While executing a threading cycle.</td>
<td>The spindle speed “S” has not been defined.</td>
<td>Program a positive spindle speed “S” other than zero.</td>
</tr>
<tr>
<td>9014</td>
<td>'THREADING: Value of P=0'</td>
<td>While executing a threading cycle.</td>
<td>The thread pitch has not been defined.</td>
<td>Program a thread pitch greater than zero.</td>
</tr>
<tr>
<td>9015</td>
<td>'THREADING: Value of H=0'</td>
<td>While executing a threading cycle.</td>
<td>The thread depth has not been defined.</td>
<td>Program a thread depth other than zero.</td>
</tr>
<tr>
<td>9016</td>
<td>'THREADING: Value of (\Delta)=0'</td>
<td>While executing a threading cycle.</td>
<td>The tapping depth (\Delta) has not been defined.</td>
<td>Program a cutting pass greater than zero.</td>
</tr>
<tr>
<td>9017</td>
<td>'THREADING: Value of (\sigma) &gt; (Zf-Zi)'</td>
<td>While executing a threading cycle.</td>
<td>The distance to the end of the thread is greater than the length of the thread.</td>
<td>Program a distance to the end of the thread smaller than the length of the thread.</td>
</tr>
<tr>
<td>9018</td>
<td>'GEOMETRY: Value of Xi=Xf'</td>
<td>While executing a threading cycle.</td>
<td>The X coordinate of the starting and end points are the same.</td>
<td>The X coordinate of the starting and end points must be different.</td>
</tr>
<tr>
<td>9019</td>
<td>'THREADING: Value of (\sigma) &gt; (Xf-Xi)'</td>
<td>While executing a threading cycle.</td>
<td>The distance to the end of the thread is greater than the length of the thread.</td>
<td>Program a distance to the end of the thread smaller than the length of the thread.</td>
</tr>
<tr>
<td>9020</td>
<td>'ROUGHING: Wrong location (shape) code'</td>
<td>While executing a grooving cycle.</td>
<td>No groove roughing can be done with the selected location code.</td>
<td>Select a tool with the right location code.</td>
</tr>
<tr>
<td>9021</td>
<td>'FINISHING: Wrong location (shape) code'</td>
<td>While executing a grooving cycle.</td>
<td>No groove finishing can be done with the selected location code.</td>
<td>Select a tool with the right location code.</td>
</tr>
</tbody>
</table>
9022 ‘GEOMETRY: Null profile’

DETECTION While executing a level-1 profile cycle.
CAUSE No profile has been defined because the starting point and the end point are the same.
SOLUTION The starting point and the end point of the profile must be different.

9023 ‘DRILLING: Value of T=0’

DETECTION While executing a drilling or multiple drilling cycle.
CAUSE The tool number has not been defined.
SOLUTION The tool number must be other than zero.

9024 ‘DRILLING: Value of Δ=0’

DETECTION While executing a drilling or multiple drilling cycle.
CAUSE The tapping depth “Δ” has not been defined.
SOLUTION Program a cutting pass greater than zero.

9025 ‘DRILLING: Value of L=0’

DETECTION While executing a drilling or multiple drilling cycle.
CAUSE The drilling depth has not been defined.
SOLUTION Program a drilling depth other than zero.

9026 ‘DRILLING: Value of F=0’

DETECTION While executing a drilling or multiple drilling cycle.
CAUSE The feedrate “F” has not been defined.
SOLUTION Program a positive feedrate “F” other than zero.

9027 ‘DRILLING: Value of S=0’

DETECTION While executing a drilling or multiple drilling cycle.
CAUSE The spindle speed “S” has not been defined.
SOLUTION Program a positive spindle speed “S” other than zero.

9028 ‘TAPPING: Value of T=0’

DETECTION While executing a tapping or multiple tapping cycle.
CAUSE The tool number has not been defined.
SOLUTION The tool number must be other than zero.

9029 ‘TAPPING: Value of L=0’

DETECTION While executing a tapping or multiple tapping cycle.
CAUSE The threading depth has not been defined.
SOLUTION Program a tapping depth other than zero.

9030 ‘TAPPING: Value of F=0’

DETECTION While executing a tapping or multiple tapping cycle.
CAUSE The feedrate “F” has not been defined.
SOLUTION Program a positive feedrate “F” other than zero.

9031 ‘TAPPING: Value of S=0’

DETECTION While executing a tapping or multiple tapping cycle.
CAUSE The spindle speed “S” has not been defined.
SOLUTION Program a positive spindle speed “S” other than zero.
<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
<th>Detection</th>
<th>Cause</th>
<th>Solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>9032</td>
<td>'GEOMETRY: The final diameter is not external'</td>
<td>While executing a turning or grooving cycle.</td>
<td>An outside turning has been defined, but the final diameter is larger than that of the starting diameter.</td>
<td>In an outside turning, the final diameter must be smaller than the starting one.</td>
</tr>
<tr>
<td>9033</td>
<td>'GEOMETRY: The final diameter is not internal'</td>
<td>While executing a turning or grooving cycle.</td>
<td>An inside turning has been defined, but the final diameter is smaller than that of the starting diameter.</td>
<td>In an inside turning, the final diameter must be larger than the starting one.</td>
</tr>
<tr>
<td>9034</td>
<td>'GEOMETRY: Wrong quadrant'</td>
<td>While executing a taper turning cycle.</td>
<td>A taper has been defined in the wrong quadrant.</td>
<td>Select the right quadrant using the relevant icon.</td>
</tr>
<tr>
<td>9035</td>
<td>'A negative safety distance is not allowed in this cycle'</td>
<td>While executing a taper turning, rounding or profiling cycle.</td>
<td>A negative safety distance has been defined.</td>
<td>In taper canned cycles, the safety distance must be positive.</td>
</tr>
<tr>
<td>9036</td>
<td>'ROUGHING: Wrong tool for GROOVING.'</td>
<td>While executing a grooving cycle.</td>
<td>The geometry of the selected tool is not right for groove roughing.</td>
<td>Select a tool with the right geometry.</td>
</tr>
<tr>
<td>9037</td>
<td>'FINISHING: Wrong tool for GROOVING.'</td>
<td>While executing a grooving cycle.</td>
<td>The geometry of the selected tool is not right for groove finishing.</td>
<td>Select a tool with the right geometry.</td>
</tr>
<tr>
<td>9038</td>
<td>'GEOMETRY: Wrong angle for GROOVING.'</td>
<td>While executing a grooving cycle.</td>
<td>The angle of the groove walls is lower than 0º or higher than 90º.</td>
<td>The angle of the groove walls must be between 0º and 90º.</td>
</tr>
<tr>
<td>9039</td>
<td>'GEOMETRY: The sides of the groove intersect each other.'</td>
<td>During execution.</td>
<td>The two walls of the groove intersect each other.</td>
<td>Check the cycle data. The walls of the groove cannot intersect each other.</td>
</tr>
<tr>
<td>9040</td>
<td>'MULTIPLE CYCLE: Value of $\beta=0$'</td>
<td>While executing a multiple drilling, multiple tapping or slot multiple milling cycle.</td>
<td>The angular step between machining has not been defined.</td>
<td>Program an angular step other than zero.</td>
</tr>
<tr>
<td>9041</td>
<td>'MULTIPLE CYCLE: Value of $N=0$'</td>
<td>While executing a multiple drilling, multiple tapping or slot multiple milling cycle.</td>
<td>The number of machining operations has not been defined.</td>
<td>The minimum number of machining operations is 1.</td>
</tr>
</tbody>
</table>
9042 ‘MULTIPLE SLOT MILLING CYCLE: Value of T=0’
DETECTION While executing a multiple slot milling cycle.
CAUSE The tool number has not been defined.
SOLUTION The tool number must be other than zero.

9043 ‘MULTIPLE SLOT MILLING CYCLE: Value of F=0’
DETECTION While executing a multiple slot milling cycle.
CAUSE The feedrate “F” has not been defined.
SOLUTION Program a positive feedrate “F” other than zero.

9044 ‘MULTIPLE SLOT MILLING CYCLE: Value of S=0’
DETECTION While executing a multiple slot milling cycle.
CAUSE No live tool turning speed “St” has been defined.
SOLUTION Program a positive turning speed “St” other than zero.

9045 ‘MULTIPLE SLOT MILLING CYCLE: Value of I=0’
DETECTION While executing a multiple slot milling cycle.
CAUSE The slot milling depth has not been defined.
SOLUTION Program a slot milling depth other than zero.

9046 ‘MULTIPLE SLOT MILLING CYCLE: Value of L=0’
DETECTION While executing a multiple slot milling cycle.
CAUSE The slot milling length has not been defined.
SOLUTION The slot length must be other than zero.

9048 ‘C AXIS PROFILE CYCLE: Value of T=0’
DETECTION While executing a profile cycle on the C axis.
CAUSE The tool number has not been defined.
SOLUTION The tool number must be other than zero.

9049 ‘C AXIS PROFILE CYCLE: Value of Δ=0’
DETECTION While executing a profile cycle on the C axis.
CAUSE The tapping depth “Δ” has not been defined.
SOLUTION Program a cutting pass greater than zero.

9050 ‘C AXIS PROFILE CYCLE: Value of I=0’
DETECTION While executing a profile cycle on the C axis.
CAUSE The total machining depth has not been defined.
SOLUTION Program a machining depth other than zero.

9051 ‘C AXIS PROFILE CYCLE: Value of F=0’
DETECTION While executing a profile cycle on the C axis.
CAUSE The feedrate “F” has not been defined.
SOLUTION Program a positive feedrate “F” other than zero.

9052 ‘C AXIS PROFILE CYCLE: Value of S=0’
DETECTION While executing a profile cycle on the C axis.
CAUSE No live tool turning speed “St” has been defined.
SOLUTION Program a positive turning speed “St” other than zero.

9053 ‘Value of Smax=0’
DETECTION While executing any cycle.
CAUSE The maximum spindle speed “Smax” has not been defined.
SOLUTION Program a maximum positive spindle speed “Smax” other than zero.
9054 'DRILLING: Value of $K_{\Delta} > 1$'

| DETECTION | While executing a drilling or multiple drilling cycle. |
| CAUSE | The gear ratio $K_{\Delta}$ with a value greater than 1. |
| SOLUTION | Program a gear ratio $K_{\Delta}$ with a value between 0 and 1. |

9055 'GEOMETRY: The tool is too big for the groove.'

| DETECTION | While executing a grooving cycle. |
| CAUSE | The diameter of the selected tool is larger than the width of the programmed groove. |
| SOLUTION | Select another tool with a smaller diameter. |

9056 'GEOMETRY: Value of $Z=R$.'

| DETECTION | While executing a grooving cycle. |
| CAUSE | When milling slots with Z axis penetration (levels 2 and 4), a slot has been programmed without penetration. |
| SOLUTION | Program the external coordinate “Z” and the depth coordinate “R” with different values. |

9057 'CUTOFF: Value of $T=0$'

| DETECTION | While executing a cut-off cycle. |
| CAUSE | The tool number has not been defined. |
| SOLUTION | The tool number must be other than zero. |

9058 'CUTOFF: Value of $F=0$'

| DETECTION | While executing a cut-off cycle. |
| CAUSE | The feedrate “F” has not been defined. |
| SOLUTION | Program a positive feedrate “F” other than zero. |

9059 'CUTOFF: Value of $S=0$'

| DETECTION | While executing a cut-off cycle. |
| CAUSE | The spindle speed “S” has not been defined. |
| SOLUTION | Program a positive spindle speed “S” other than zero. |

9060 'CUTOFF: Value of $Fr=0$'

| DETECTION | While executing a cut-off cycle. |
| CAUSE | The cut-off feedrate “Fr” has not been defined. |
| SOLUTION | Program a positive cut-off feedrate “Fr” other than zero. |

9061 'CUTOFF: Value of $Fr > F$'

| DETECTION | While executing a cut-off cycle. |
| CAUSE | The cut-off feedrate “Fr” is higher than the feedrate “F”. |
| SOLUTION | Program a smaller cut-off feedrate “Fr” than the feedrate “F”. |

9062 'DRILLING: Value of minimum increment > $\Delta$'

| DETECTION | While executing a drilling cycle. |
| CAUSE | The minimum increment is larger than the drilling peck “$\Delta$”. |
| SOLUTION | Program a smaller minimum increment than the drilling peck “$\Delta$”. |

9063 'TOOL CALIBRATION: Value of $T=0$'

| DETECTION | While executing a tool calibration cycle. |
| CAUSE | The tool number has not been defined. |
| SOLUTION | The tool number must be other than zero. |
9064 ‘PROBE CALIBRATION: Value of T=0’

DETECTION While executing a probe calibration cycle.
CAUSE The tool number has not been defined.
SOLUTION The tool number must be other than zero.

9065 ‘RECTANGULAR POCKET: F=0’

DETECTION While executing a rectangular pocket cycle.
CAUSE The feedrate “F” has not been defined.
SOLUTION Program a positive feedrate “F” other than zero.

9066 ‘RECTANGULAR POCKET: S=0’

DETECTION While executing a rectangular pocket cycle.
CAUSE No live tool turning speed “S” has been defined.
SOLUTION Program a positive spindle speed “S” other than zero.

9067 ‘RECTANGULAR POCKET: P=0’

DETECTION While executing a rectangular pocket cycle.
CAUSE The total pocket depth has not been defined.
SOLUTION Program a total pocket depth greater than zero.

9068 ‘RECTANGULAR POCKET: Wrong penetration angle’

DETECTION While executing a rectangular pocket cycle.
CAUSE The defined penetration angle is wrong.
SOLUTION Program a penetration angle greater than 0º and smaller than or equal to 90º.

9069 ‘RECTANGULAR POCKET: Tool diameter smaller than ∆’

DETECTION While executing a rectangular pocket cycle.
CAUSE The tool diameter is smaller than the maximum roughing pass «∆».
SOLUTION The tool diameter must be equal to or greater than the maximum roughing pass «∆».

9070 ‘RECTANGULAR POCKET: Tool diameter larger than pocket’

DETECTION While executing a rectangular pocket cycle.
CAUSE The tool diameter is larger than the pocket.
SOLUTION The tool diameter must be smaller than the pocket’s «L» and «H» dimensions of the pocket.

9071 ‘RECTANGULAR POCKET: Tool diameter FINISHING STOCK less than δ’

DETECTION While executing a rectangular pocket cycle.
CAUSE The diameter of the finishing tool is smaller than the finishing stock «δ».
SOLUTION The diameter of the tool must be greater than the finishing stock «δ».

9072 ‘CIRCULAR POCKET: F=0’

DETECTION While executing a circular pocket cycle.
CAUSE The feedrate “F” has not been defined.
SOLUTION Program a positive feedrate “F” other than zero.

9073 ‘CIRCULAR POCKET: S=0’

DETECTION While executing a circular pocket cycle.
CAUSE No live tool turning speed “S” has been defined.
SOLUTION Program a positive spindle speed “S” other than zero.

9074 ‘CIRCULAR POCKET: P=0’

DETECTION While executing a circular pocket cycle.
CAUSE The total pocket depth has not been defined.
SOLUTION Program a total pocket depth greater than zero.
9075 'CIRCULAR POCKET: Wrong penetration angle'

DETECTION While executing a circular pocket cycle.
CAUSE The defined penetration angle is wrong.
SOLUTION Program a penetration angle greater than 0º and smaller than or equal to 90º.

9076 'CIRCULAR POCKET: Tool diameter smaller than ∆'

DETECTION While executing a circular pocket cycle.
CAUSE The tool diameter is smaller than the maximum roughing pass «∆».
SOLUTION The tool diameter must be equal to or greater than the maximum roughing pass «∆».

9077 'CIRCULAR POCKET: Tool diameter larger than pocket'

DETECTION While executing a circular pocket cycle.
CAUSE The tool diameter is larger than that of the pocket.
SOLUTION The diameter of the tool must be smaller than the diameter of the pocket (2Rc).

9078 'CIRCULAR POCKET: Tool diameter FINISHING STOCK less than δ'

DETECTION While executing a circular pocket cycle.
CAUSE The diameter of the finishing tool is smaller than the finishing stock «δ».
SOLUTION The diameter of the tool must be greater than the finishing stock «δ».

9079 'RECTANGULAR POCKET: δ not valid'

DETECTION While executing a rectangular pocket cycle.
CAUSE The defined finishing stock «δ» is not valid.
SOLUTION Reduce the value of the finishing stock «δ».

9080 'POSITIONING: Value of T=0'

DETECTION While executing a positioning cycle.
CAUSE The tool number has not been defined.
SOLUTION The tool number must be other than zero.

9081 'PROFILE POCKET: F=0'

DETECTION While executing a profile pocket cycle.
CAUSE The feedrate “F” has not been defined.
SOLUTION Program a positive feedrate “F” other than zero.

9082 'PROFILE POCKET: S=0'

DETECTION While executing a profile pocket cycle.
CAUSE No live tool turning speed “S” has been defined.
SOLUTION Program a positive spindle speed “S” other than zero.

9083 'PROFILE POCKET: Wrong penetration angle'

DETECTION While executing a profile cycle.
CAUSE The defined penetration angle is wrong.
SOLUTION Program a penetration angle greater than 0º and smaller than or equal to 90º.

9084 'PROFILE POCKET: Tool diameter smaller than ∆'

DETECTION While executing a profile pocket cycle.
CAUSE The tool diameter is smaller than the maximum roughing pass «∆».
SOLUTION The tool diameter must be the same as or larger than the maximum roughing pass «∆».

9085 'PROFILE POCKET: Tool diameter FINISHING STOCK less than δ'

DETECTION While executing a profile pocket cycle.
CAUSE The diameter of the finishing tool is smaller than the finishing stock «δ».
SOLUTION The diameter of the tool must be greater than the finishing stock «δ».
**9081 ‘PROFILE POCKET: P=0’**

<table>
<thead>
<tr>
<th>DETECTION</th>
<th>While executing a profile pocket cycle.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAUSE</td>
<td>The total pocket depth has not been defined.</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>Program a total pocket depth greater than zero.</td>
</tr>
</tbody>
</table>